

1. Record Nr.	UNISOBE600200006277
Autore	Norberg, Dag
Titolo	Au seuil du moyen age : Etudes linguistiques, métriques et littéraires publiées par ses collègues et élèves à l'occasion de son 65. anniversaire / Dag Norberg
Pubbl/distr/stampa	Padova : Antenore, 1974
Descrizione fisica	176 p., [1] c. di tav. : ritr. ; 25 cm
Collana	Medioevo e umanesimo ; 19
Lingua di pubblicazione	Italiano
	Francese
Formato	Materiale a stampa
Livello bibliografico	Monografia
2. Record Nr.	UNINA9910457720403321
Titolo	The Russian peasant, 1920 and 1984 [[electronic resource] /] / edited by R. E. F. Smith
Pubbl/distr/stampa	London, : Cass, 1977
ISBN	1-135-78150-8 1-280-15433-0 0-203-98922-8
Descrizione fisica	1 online resource (132 p.)
Collana	Library of peasant studies ; no. 4
Altri autori (Persone)	SmithR. E. F (Robert E. F.)
Disciplina	301.44/43 301.4443 306/.0947
Soggetti	Peasants - Soviet Union Electronic books. Soviet Union Rural conditions
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Description based upon print version of record.

Nota di bibliografia

Includes bibliography: p. 119-120.

Nota di contenuto

The Russian Peasant 1920 and 1984; Copyright; Contents; Editors' Introduction; Introduction; Note on the Sources of George Orwell's 1984; On the Russian Peasantry; The Soviet Countryside 1917-1924; Contents; An Average Farm, its Income and the Family Budget; Comparative Burden of Taxation on the Land; Results; Commerce, Crafts and Trades; The Grain Loan; The Journey of my Brother Alexei to the Land of Peasant Utopia; Contents; Foreword; PART 1 The Appearance

Chapter 1 In which the well-disposed reader becomes acquainted with the triumph of socialism and Alexei Kremnev, the hero of our story.

Chapter 2 Telling of the influence of Herzen on the inflamed imagination of a Soviet official.; Chapter 3 Depicting Kremnev's appearance in the land of Utopia and his pleasant conversation with a Utopian Moscow girl on the history of twentieth century painting.; Chapter 4 Continuing the third and separated from it only in order to avoid excessively lengthy chapters.; Chapter 5 Excessively long, but essential to acquaint Kremnev with Moscow in 1984.

Chapter 6 In which the reader will conclude that after 80 years they have not forgotten in Archangel'skoe how to make vanilla cheese-cake for tea. Chapter 7 Convincing those so inclined that the family is the family, and ever shall be.; Chapter 8 Historical; Chapter 9 Which young lady readers may skip, but which is recommended for the particular attention of members of the Communist Party.; Chapter 10 In which the fair at White Kolp' is described and the author's complete agreement with Anatole France's dictum that a story without love is like fat without mustard is explained.

Chapter 11 Very similar to Chapter 9 Chapter 12 Describing the considerable improvement in Moscow's museums and places of entertainment and cut short by an exceedingly unpleasant surprise.; Chapter 13 Acquainting Kremnev with the bad organisation of places of confinement in the land of Utopia and with certain forms of Utopian judicial procedure.; Chapter 14 And the last in the first part, which demonstrates both that sometimes ploughshares may be successfully turned into swords and that Kremnev finally turned out to be in an exceedingly piteous situation.; The Sign of the Zodiac Note on Russian Terms Bibliography

Sommario/riassunto

First published in 1977, The Russian Peasant 1920 and 1984 is a significant contribution to history.

3. Record Nr.	UNINA9910231245303321
Autore	Ben-Ari Mordechai
Titolo	Elements of Robotics [[electronic resource] /] / by Mordechai Ben-Ari, Francesco Mondada
Pubbl/distr/stampa	Springer Nature, 2017 Cham : , : Springer International Publishing : , : Imprint : Springer, , 2018
ISBN	3-319-62533-0
Edizione	[1st ed. 2018.]
Descrizione fisica	1 online resource (XVI, 308 p. 198 illus., 76 illus. in color.)
Disciplina	006.3
Soggetti	Artificial intelligence Algorithms Robotics Automation Artificial Intelligence Robotics and Automation
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Nota di contenuto	Robots and their Applications -- Sensors -- Reactive Behavior -- Finite State Machines -- Robotic Motion and Odometry -- Control -- Local Navigation: Obstacle Avoidance -- Localization -- Mapping -- Mapping-based Navigation -- Fuzzy Logic Control -- Image Processing -- Neural Networks -- Machine Learning -- Swarm Robotics -- Kinematics of a Robotic Manipulator -- Appendix A: Units of Measurement -- Appendix B: Mathematical Derivations and Tutorials -- Index.
Sommario/riassunto	This book is open access under a CC BY 4.0 license. This book bridges the gap between playing with robots in school and studying robotics at the upper undergraduate and graduate levels to prepare for careers in industry and research. Robotic algorithms are presented formally, but using only mathematics known by high school and first-year college students, such as calculus, matrices and probability. Concepts and algorithms are explained through detailed diagrams and calculations. Elements of Robotics presents an overview of different types of robots

and the components used to build robots, but focuses on robotic algorithms: simple algorithms like odometry and feedback control, as well as algorithms for advanced topics like localization, mapping, image processing, machine learning and swarm robotics. These algorithms are demonstrated in simplified contexts that enable detailed computations to be performed and feasible activities to be posed. Students who study these simplified demonstrations will be well prepared for advanced study of robotics. The algorithms are presented at a relatively abstract level, not tied to any specific robot. Instead a generic robot is defined that uses elements common to most educational robots: differential drive with two motors, proximity sensors and some method of displaying output to the user. The theory is supplemented with over 100 activities, most of which can be successfully implemented using inexpensive educational robots. Activities that require more computation can be programmed on a computer. Archives are available with suggested implementations for the Thymio robot and standalone programs in Python.

4. Record Nr.	UNIORUON00429721
Autore	LOTHE, Jakob
Titolo	Conrad's narrative method / Jakob Lothe
Pubbl/distr/stampa	Oxford, : Clarendon, 1989
Descrizione fisica	xi, 315 p. ; 22 cm.
Disciplina	820.09
Soggetti	CONRAD JOSEPH
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia