

1. Record Nr.	UNISALENTO991002568089707536
Autore	Bacherini, Anna Maria
Titolo	Minori in affido : un aggiornamento per educatrici dei Villaggi SOS / Anna Maria Bacherini, Giuseppina Arrighi, Corrado Bogliolo
Pubbl/distr/stampa	Tirrenia : Edizioni del Cerro, [2003]
ISBN	8882161110
Descrizione fisica	101 p. ; 23 cm
Altri autori (Persone)	Arrighi, Giuseppinaauthor Bogliolo, Corrado
Disciplina	362.733
Soggetti	Affido familiare
Lingua di pubblicazione	Italiano
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2.	Record Nr.	UNISALENTO991003724589707536
	Autore	Pachman, Ludek
	Titolo	El match del siglo : Fischer-Spassky : campeonato del mundo 1972 / Ludeck Pachman
	Pubbl/distr/stampa	Barcelona : Roca, 1972
	ISBN	8427002009
	Descrizione fisica	134 p. : ill. ; 20 cm
	Collana	Escaques ; 40
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	Soggetti	Partite a scacchi - Sfida Fischer-Spassky
	Lingua di pubblicazione	Spagnolo
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3.	Record Nr.	UNINA9910964074603321
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	Pubbl/distr/stampa	Amsterdam ; ; Washington, D.C., : IOS Press, 2010
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	Altri autori (Persone)	ChristensenHenrik I GroenF. C. A PetriuEmil
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Nota di bibliografia

Includes bibliographical references and indexes.

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and RFID -- Recognizing Nonverbal Affective Behavior in Humanoid
Robots -- Feasibility of Interactive Localization and Navigation of
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Unsupervised Learning of Gaussian Mixture Models by Means of a
Binary Tree Structure -- On Ambiguity in Robot Learning from
Demonstration -- Recognition and Motion Primitives for Autonomous
Clothes Unfolding of Humanoid Robot -- Perception -- 3D Sensing
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Pose Estimation Methods for Stereo Visual Odometry on Robots --
Object Search on a Mobile Robot Using Relational Spatial Information --
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Sensing to Improve Control on Solution Quality -- Selection of
Parameters and Algorithms in Multiple-Goal Task Realization --
Smooth Autonomous Driving on Braunschweig's Inner Ring Road --
Distributed Systems -- Behavior-Based Control of Self-Reconfigurable
Robot Teams for Sensor Placement.
Improving Market-Based Task Allocation with Optimal Seed Schedules
-- A Thermodynamic Framework for Robot Colony Control -- Map-
Merging-Free Connectivity Positioning for Distributed Robot Teams --
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Sommario/riassunto

This volume contains the proceedings of the eleventh International
Conference on Intelligent Autonomous Systems (IAS-11) at the
University of Ottawa in Canada. As ever, the purpose of the IAS
conference is to bring together leading international researchers with
an interest in all aspects of the autonomy and adaptivity of artificial
systems. This year the conference reflects in particular a current trend:
the symbiotic interaction of humans with intelligent systems. Of the 35
papers submitted for this year's conference, 25 have been accepted for
presentation. These papers cover a wide spectrum of research in
autonomous intelligent systems including interactive systems, learning,
perception, localization and mapping, navigation planning and
distributed systems. This proceedings includes all the accepted papers
and reflects the wide variety of topics of current concern to all those
involved in the use, research and development of intelligent
autonomous systems.