

1. Record Nr.	UNINA990002647560403321
Autore	Roll, Eric
Titolo	Il mondo dopo Keynes / Eric Roll
Pubbl/distr/stampa	Bologna, : il Mulino, 1971
Descrizione fisica	317 p. ; 22 cm
Collana	Saggi ; 104
Disciplina	334 330.156
Locazione	DECTS ECA DTE FLFBC DFD DECSE FSPBC
Collocazione	ISVE B1-B3.49 9-0-26-TI XV E132 XV F 81 334 ROL 1 XI EE R 3(1) SE 100.02.14- SE 030.08.11- COLLEZ. 75 (104) 330.156 ROL 1
Lingua di pubblicazione	Italiano
Formato	Materiale a stampa
Livello bibliografico	Monografia

2. Record Nr. UNISALENTO991003256409707536  
Autore Sarotti, Mario  
Titolo Igiene puericultura economia domestica : educare oggi nella scuola materna / Mario Sarotti, Giovanni Sciacovelli  
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Pubbl/distr/stampa Bergamo : Continental, 1977  
-----  
Descrizione fisica 191 p. ; 24 cm.  
-----  
Altri autori (Persone) Sciacovelli, Giovanniauthor  
-----  
Disciplina 613  
Soggetti Igiene  
Puericultura  
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Lingua di pubblicazione Italiano  
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Formato Materiale a stampa  
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Livello bibliografico Monografia  
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3. Record Nr. UNISALENTO991001365389707536  
Titolo Dire Dio al femminile : antropologia e teologia / a cura di Angelo Sabatelli  
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Pubbl/distr/stampa Roma : Edizioni Vivere in, 2003  
-----  
Descrizione fisica 58 p. ; 24 cm.  
-----  
Collana Quaderni della Rivista di scienze religiose ; 1  
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Altri autori (Persone) Sabatelli, Angelo  
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Disciplina 261.8344  
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Lingua di pubblicazione Non definito  
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Formato Materiale a stampa  
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Livello bibliografico Monografia  
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4. Record Nr.	UNINA9910586583403321
Titolo	Intelligent Robotics and Applications : 15th International Conference, ICIRA 2022, Harbin, China, August 1–3, 2022, Proceedings, Part I // edited by Honghai Liu, Zhouping Yin, Lianqing Liu, Li Jiang, Guoying Gu, Xinyu Wu, Weihong Ren
Pubbl/distr/stampa	Cham : , : Springer International Publishing : , : Imprint : Springer, , 2022
ISBN	3-031-13844-9
Edizione	[1st ed. 2022.]
Descrizione fisica	1 online resource (801 pages)
Collana	Lecture Notes in Artificial Intelligence, , 2945-9141 ; ; 13455
Disciplina	006.3 629.89263
Soggetti	Artificial intelligence Software engineering Application software User interfaces (Computer systems) Human-computer interaction Computer networks Computers, Special purpose Artificial Intelligence Software Engineering Computer and Information Systems Applications User Interfaces and Human Computer Interaction Computer Communication Networks Special Purpose and Application-Based Systems
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Nota di contenuto	Vision-Based Human-Robot Interaction and Applications -- Interaction, Control and Application Technologies of Welfare Robots -- AI Meets the Challenges of Autism -- Space Robot and Space Mechanism -- Mechanism Design, Control and Application of Reconfigurable Robots -- Autonomous Intelligent Robot Systems for Unconstrained Environments -- Rehabilitation and Assistive Robotics -- Learning from

Human Demonstrations for Redundant Manipulator -- Mechanism Design, Control and Sensing of Soft Robots -- Intelligent Perception and Control of Rehabilitation Systems -- Actuation, Sensing and Control of Soft Robots -- Actuation, Sensing and Control of Soft Robots -- Machine Vision for Intelligent Robotics -- Micro or Nano Robotics and Its Application -- Biosignal Acquisition and Analysis -- Neurorobotics -- Wearable Sensing and Robot Control -- Wearable Robotics to Characterize, Retrain, and Restore Human Movements -- Robotic Environment Perception -- Swarm Robotic Technology and System in Space and Underwater -- Medical Robot -- Intelligent Cooperation in Mobile Robots for Learning, Optimization, Planning, and Control -- Tactile Robotics -- Co-Manipulation System with Enhanced Human-Machine Perception -- Compliant Mechanisms and Robotic Applications -- Flexible or Continuum Robots in Clinical Context -- Data Processing and Image Analysis -- Advanced Key Technologies in Intelligent Interactive Robots -- Sensing and Decoding of Biosignals for Human-Machine -- Intelligent Vision and Learning -- Machine Learning in Human-Robot Collaboration -- Multimodal Sensing and Understanding -- Bio-Inspired Healthcare Robotics and Technology -- Robot Vision and Applications.

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Sommario/riassunto

The 4-volume set LNAI 13455 - 13458 constitutes the proceedings of the 15th International Conference on Intelligent Robotics and Applications, ICIRA 2022, which took place in Harbin China, during August 2022. The 284 papers included in these proceedings were carefully reviewed and selected from 442 submissions. They were organized in topical sections as follows: Robotics, Mechatronics, Applications, Robotic Machining, Medical Engineering, Soft and Hybrid Robots, Human-robot Collaboration, Machine Intelligence, and Human Robot Interaction.

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