

1.	Record Nr.	UNINA990003212200403321
	Titolo	Super State : Readings in the Military-Industrial Complex / Edited by Herbert I. Schiller and Joseph D. Phillips.
	Pubbl/distr/stampa	Urbana, Ill. : University of Illinois Press, 1972
	ISBN	0-252-00283-0
	Descrizione fisica	XI, 351 p. ; 23 cm
	Disciplina	F/1.221 N/1.6
	Locazione	SE
	Collocazione	S F/1.221 SUP
	Lingua di pubblicazione	Italiano
	Formato	Materiale a stampa
	Livello bibliografico	Monografia
2.	Record Nr.	UNISALENTO991000477429707536
	Titolo	Aggregation operators : new trends and applications / Tomasa Calvo, Gaspar Mayor, Radko Mesiar, editors
	Pubbl/distr/stampa	Heidelberg : Physica-Verlag, c2002
	ISBN	3790814687
	Descrizione fisica	xiv, 352 p. : ill. ; 24 cm
	Collana	Studies in fuzziness and soft computing, 1434-9922 ; 97
	Classificazione	AMS 94D05 LC QA329.A38
	Altri autori (Persone)	Calvo, Tomasaauthor Mayor, Gasparauthor Mesiar, Radkoauthor
	Disciplina	515.724
	Soggetti	Aggregation operators Soft computing Fuzzy logic
	Lingua di pubblicazione	Inglese
	Formato	Materiale a stampa
	Livello bibliografico	Monografia

Nota di bibliografia	Includes bibliographical references
3. Record Nr.	UNISA996574588703316
Titolo	2019 3rd Conference on Vehicle Control and Intelligence (CVCI 2019) : Hefei, China, 21 - 22 September 2019 / / Institute of Electrical and Electronics Engineers
Pubbl/distr/stampa	Pistacaway, New Jersey : , : IEEE, , [2019] ©2019
ISBN	1-7281-2683-5
Descrizione fisica	1 online resource (441 pages) : illustrations
Disciplina	629.046
Soggetti	Motor vehicles - Automatic control Transportation - Automation Intelligent control systems
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Includes index.
Nota di contenuto	Fuzzy-Sliding Mode Control based Yaw Stability Control Algorithm for Four-in-wheel-motor Drive Electric Vehicle -- Research on Dynamic Characteristics of Lateral Sloshing in Liquid Tank Semi-trailer -- Study on Dynamic Characteristics of Longitudinal Sloshing in Liquid Tank Semi-trailer -- Research on Model Predictive Control Method for Multi-paralleled DC-DC Converters -- Research on track reckoning of Automatic Parking System Based on Multi-information Fusion -- Direct Torque Control of A Segmented Switched Reluctance Motor for BSG in HEVs -- A High Precision Vehicle Tracking Algorithm Based on Digital Image Correlation -- Inconsistency Eect of Internal Resistance on Performance of Lithium-ion Battery Strings -- State Observer-Based Air-Fuel Ratio Regulation of Compressed Natural Gas Engines -- Stochastic Adaptive Tracking Control of Electronic Throttle -- Optimization of Control Strategy for Dual-motor Coupled Propulsion System Based on Dynamic Programming Method -- High-Precision Parameter Identification of Lithium-ion Battery Based on Voltage Signal Reconstruction -- A Camera-IMU Sensor Fusion for Robust Lane

Information on Lateral Control System -- MPC-based fault tolerant control system for yaw stability of distributed drive electric vehicle -- Predictive Freeway Overtaking Strategy for Automated Vehicles Using Deep Reinforcement Learning -- Takagi-Sugeno fuzzy control for the semi-active seat suspension with an electromagnetic damper -- A finite-time estimation algorithm for updating look-up tables -- Transient Dynamic Response Analysis of Engine Start for A Hybrid Electric Vehicle -- Trajectory Planning and Tracking for Autonomous Vehicle Considering Human Driver Personality -- Energy Management Strategy of Plug-in Hybrid Electric Vehicles Considering the Temperature Effect of Power Battery -- Fuzzy Logic Energy Management Strategy Based on Genetic Algorithm for Plug-in Hybrid Electric Vehicles -- Dynamic Programming Algorithm for Energy Management Strategy of Fuel Cell Electric Vehicle -- Adaptive Tracking Control for Active Seat Suspension System with Time-Varying Full State Constraints -- The electronic throttle controller based on the model reference adaptive nonlinear triple-step method -- Fast Segmentation of 3-D Point Clouds Based on Ground Plane State Tracking -- Optimization design and evaluation of shift point for electric bus based on multi-objective genetic algorithm -- Connected Cruise Control Based on Adaptive Dynamic Programming Considering Inertial Delay -- Hardware-in-the-loop simulation of electronic differential moment power steering control strategy for multi-axle vehicle -- Internal Short Circuit Fault Diagnosis for Lithium-ion Battery Based on Voltage and Temperature -- Experimental investigation of water-cooling based thermal management for cylindrical Li-ion batteries -- Topology optimization design of 24GHz high gain microstrip antenna with metamaterial cover -- Study on the Effect of Different AC Excitations on the Internal Heating for Low-Temperature Batteries -- A Review on Source Seeking Control and Its Application to Wheeled Mobile Robots -- Research on Mechanism and Key Technology of Intelligent Vehicles Brake By Wire system -- Influence of interconnect resistances on parallel-connected LiFePO₄ cells performance -- Lateral Stability Control of Four-wheel Steering Vehicles -- Tracking of High-speed Emergency Avoidance Paths for Vehicles Based on Non-linear Active Disturbance Rejection Control -- Predictive Ecological Control: Using Road Terrain and Trac Signal Information for Improving Vehicle Energy Efficiency -- Distributed Control Design based on Multi-Agent for Distributed Driving Electric Vehicle -- Performance Study of Direct Injection Gasoline Engine Based on Hydrogen Injection Strategy -- An Optimal Trajectory Planning for Autonomous Vehicles Based on Vehicle Dynamics Constraints -- Decision-Making for Oncoming Trac Overtaking Scenario using Double DQN -- Research on Strategy and Algorithm of Lateral Motion Control for Autonomous Driving Electric Vehicle -- Study of Comprehensive Evaluation for L2 Automated Vehicles on Field Test -- Degree of Hybridization Design for a Fuel Cell/Battery Hybrid Electric Vehicle Based on Multi-objective Particle Swarm Optimization -- Real-Time Estimation of Inertial Parameter for Lightweight Electric Vehicle Using Dual Kalman Filter -- Analysis of the Efficiency of Two Different Electric-continuously Variable Transmission for Hybrid Electric Bus -- A Novel Gearshift Control Method based on Historical Driving Information -- Simulation of energy control strategy for hybrid electric vehicle based on modified dynamic programming -- Research on Electric Bulldozer Straight Driving Stability -- Study on the Estimation Method of the Forces on Vehicle Tires for ESC System -- Speed Control of Four-Wheel Independently Actuated Vehicle based on MPC Algorithm -- DOS-Robust Dynamic Speed Tracking Controller for an Integrated Motor-Gearbox Powertrain System of a Connected Car --

Personalized Controller Design for an Electro-mechanical Booster Braking System -- Preparation of RGO/Ni Nanoparticles with high-performance microwave absorption -- Thermal behavior analysis of Pouch Lithium ion Battery using distributed electro-thermal model -- A Novel Three-Phase Single-Stage Isolated AC-DC Converter with Symmetrical Structure for Battery Charger -- On Development of An Autonomous Ball Collecting Wheeled Mobile Robot -- Machine learning algorithm based battery modeling and management method: A Cyber-Physical System perspective -- Intelligent Vehicle Collision Risk Modeling and Comprehensive Evaluation Method -- A Real-time and Parameterized Optimal Torque Distribution Strategy for 4WID Electric Vehicle without Road Adhesion Information -- A Nonlinear Model Predictive Controller Design for Electronic Throttle -- ADRC-Based Active Front Steering Strategy for Path Tracking of A Farm Vehicle -- Shift Quality Improvement of AMT by Using Torque Observer and Anti-Disturbance Controller -- First step to human-steering system modelling and control- Stretch reex characteristics of driver's upper limb muscles -- Sensorless Vector Control of Permanent Magnet Synchronous Motor Based on DSP -- A real-time dynamic trajectory planning for autonomous driving vehicles -- Design and Optimization of the Shift Schedule and Gear Ratios for a Two-speed Pure Electric Logistics Vehicle -- Frictional-electro Composite Braking System Based On Dual Brake Pedal -- Accurate Torque Control of Hybrid Engine Based on Transient Air Intake Observation -- A Multi-Cell-to-Multi-Cell Equalizer for Series-Connected Batteries Based on Flyback Conversion -- A Zero-Current-Switching Heater Based on Four-Resonant-State LC Converter for Low-Temperature Lithium-Ion Batteries of Electric Vehicles -- Stochastic Model Predictive Control Design for Gasoline Engines with EGR -- GA-based Velocity Planning Using Jerk as the Encoding Method for Autonomous Vehicles -- Lateral Positioning Method for Unmanned Roller Compactor Based on Visual Feature Extraction -- Development and Application of Unmanned Virtual Simulation HIL Testing Platform -- Path tracking control based on Deep reinforcement learning in Autonomous driving -- Adaptive Output Voltage Tracking Control for a Fuel Cell-Boost Converter Power Supply -- A travel classification method suitable for optimal control of electric vehicle operation -- Study on sensitivity of internal states to operating conditions within PEM fuel cell -- Modelling of a polymer electrolyte membrane fuel cell system with anodic and cathodic internal recirculation.
