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| 1. Record Nr. | UNISALENTO991000177209707536 |
| Autore | Gentile, Giovanni <1875-1944> |
| Titolo | Storia della filosofia italiana, fino a Lorenzo Valla / Giovanni Gentile |
| Pubbl/distr/stampa | Firenze : Sansoni, 1962 |
| Edizione | [2. ed. riveduta /] |
| Descrizione fisica | 399 p. ; 21 cm. |
| Collana | Opere di Giovanni Gentile ; 11 |
| Altri autori (Persone) | Bellezza, Vito A. |
| Disciplina | 195 |
| Lingua di pubblicazione | Italiano |
| Formato | Materiale a stampa |
| Livello bibliografico | Monografia |
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| 2. Record Nr. | UNINA9910586590403321 |
| Titolo | Intelligent Robotics and Applications : 15th International Conference, ICIRA 2022, Harbin, China, August 1–3, 2022, Proceedings, Part II / / edited by Honghai Liu, Zhouping Yin, Lianqing Liu, Li Jiang, Guoying Gu, Xinyu Wu, Weihong Ren |
| Pubbl/distr/stampa | Cham : , : Springer International Publishing : , : Imprint : Springer, , 2022 |
| ISBN | 3-031-13822-8 |
| Edizione | [1st ed. 2022.] |
| Descrizione fisica | 1 online resource (813 pages) |
| Collana | Lecture Notes in Artificial Intelligence, , 2945-9141 ; ; 13456 |
| Disciplina | 629.892 |
| Soggetti | Artificial intelligence
Application software
User interfaces (Computer systems)
Human-computer interaction
Computer networks
Computers, Special purpose
Computer systems
Artificial Intelligence
Computer and Information Systems Applications
User Interfaces and Human Computer Interaction
Computer Communication Networks |

Special Purpose and Application-Based Systems
Computer System Implementation

Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Nota di contenuto	<p>Systems for Unconstrained Environments -- Rehabilitation and Assistive Robotics -- Learning from Human Demonstrations for Redundant Manipulator -- Mechanism Design, Control and Sensing of Soft Robots -- Intelligent Perception and Control of Rehabilitation Systems -- Actuation, Sensing and Control of Soft Robots -- Actuation, Sensing and Control of Soft Robots -- Machine Vision for Intelligent Robotics -- Micro or Nano Robotics and Its Application -- Biosignal Acquisition and Analysis -- Neurorobotics -- Wearable Sensing and Robot Control -- Wearable Robotics to Characterize, Retrain, and Restore Human Movements -- Robotic Environment Perception -- Swarm Robotic Technology and System in Space and Underwater -- Medical Robot -- Intelligent Co-operation in Mobile Robots for Learning, Optimization, Planning, and Control -- Tactile Robotics -- Co-Manipulation System with Enhanced Human-Machine Perception -- Compliant Mechanisms and Robotic Applications -- Flexible or Continuum Robots in Clinical Context -- DataProcessing and Image Analysis -- Advanced Key Technologies in Intelligent Interactive Robots -- Sensing and Decoding of Biosignals for Human-Machine -- Intelligent Vision and Learning -- Machine Learning in Human-Robot Collaboration -- Multimodal Sensing and Understanding -- Bio-Inspired Healthcare Robotics and Technology -- Robot Vision and Applications.</p>
Sommario/riassunto	<p>The 4-volume set LNAI 13455 - 13458 constitutes the proceedings of the 15th International Conference on Intelligent Robotics and Applications, ICIRA 2022, which took place in Harbin China, during August 2022. The 284 papers included in these proceedings were carefully reviewed and selected from 442 submissions. They were organized in topical sections as follows: Robotics, Mechatronics, Applications, Robotic Machining, Medical Engineering, Soft and Hybrid Robots, Human-robot Collaboration, Machine Intelligence, and Human Robot Interaction.</p>