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Titolo	Women with visible and invisible disabilities : multiple intersections, multiple issues, multiple therapies / / Martha E. Banks, Ellyn Kaschak, editors
Pubbl/distr/stampa	London ; ; New York : , : Routledge, , 2013
ISBN	0-7890-1937-X 1-317-71881-X 1-315-78587-0 1-317-71882-8
Edizione	[1st ed.]
Descrizione fisica	1 online resource (428 p.)
Collana	Women & Therapy ; ; Volume 26, Number 1/2 and 3/4
Altri autori (Persone)	BanksMartha E KaschakEllyn <1943->
Disciplina	362.4/082 362.4082
Soggetti	Women with disabilities
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	". has been co-published simultaneously as Women & therapy, Volume 26, Numbers 1/2 and 3/4, 2003." First published 2003 by the Haworth Press.
Nota di contenuto	Cover; Half Title; Title Page; Copyright Page; Table of Contents; Foreword; Preface; VISIBLE AND INVISIBLE IMPAIRMENTS EXPERIENCED BY WOMEN; MEN'S" ILLNESS OVERLOOKED IN WOMEN AND "WOMEN'S" ILLNESS MISDIAGNOSED OR DISMISSED; Women Living with Traumatic Brain Injury: Social Isolation, Emotional Functioning and Implications for Psychotherapy; African American Women Living with HIV/AIDS: Mental Health Issues; Chronic Pain Syndromes and Violence Against Women; Eating Disorders Among Urban and Rural African American and European American Women; DORMANT AND PART-TIME DISABILITIES The Influence of Silent Learning Disorders on the Lives of WomenPart-Time Disabled Lesbian Passing on Roller Blades, or PMS, Prozac, and Essentializing Women's Ailments; PERSONAL AND INTERPERSONAL CONCERNS FOR WOMEN WITH DISABILITIES; SOCIAL CONSTRUCTION OF DISABILITY: IMPACT ON IDENTITY; Chronic Disease Health Beliefs and Lifestyle Practices Among Vietnamese Adults: Influence of Gender and

Age; Keep Moving: Conceptions of Illness and Disability of Middle-Aged African-American Women with Arthritis; To Be or Not to Be Disabled ACCOMMODATION IN EDUCATION AND EMPLOYMENT: APPLICATION OF THE AMERICANS WITH DISABILITIES ACTADA Accommodation of Therapists with Disabilities in Clinical Training; Obsessive Compulsive Disorder in the Workplace: An Invisible Disability; SEXUALITY ISSUES: "WHO?!" "NO!" AND "HOW?"; Representations of Disability and the Interpersonal Relationships of Women with Disabilities; "People Tell Me I Can't Have Sex": Women with Disabilities Share Their Personal Perspectives on Health Care, Sexuality, and Reproductive Rights Sexual Options for People with Disabilities: Using Personal Assistance Services for Sexual ExpressionWORST CASE SCENARIOS: INTERSECTIONS OF GENDER, DISABILITY, ETHNICITY, CLASS AND SOCIAL DISAPPROVAL; Substance Abuse, Disabilities, and Black Women: An Issue Worth Exploring; Women with Physical Disabilities Who Want to Leave Their Partners: A Feminist and Disability-Affirmative Perspective; Prostitution and the Invisibility of Harm; EMPOWERMENT: USING CULTURE AND CONTEXT TO ENHANCE AND FACILITATE FEMINIST THERAPY; INTEGRATING SPIRITUALITY, HISTORY, AND WOMEN'S WAYS OF KNOWING INTO THERAPY Prayer as Interpersonal Coping in the Lives of Mothers with HIVThe Call of the Wild Woman: Models of Healing; ONE SIZE DOES NOT FIT ALL: INTEGRATING MULTIPLE ISSUES INTO FEMINIST THERAPY FOR WOMEN WITH DISABILITIES; Special Issues in Psychotherapy with Minority Deaf Women; Womanist Therapy with African American Women with Disabilities; Assessment, Treatment, and Rehabilitation for Interpersonal Violence Victims: Women Sustaining Head Injuries; Index

#### Sommario/riassunto

This thoughtful collection addresses the issues faced by women with disabilities, examines the social construction of disability, and makes suggestions for the development and modification of culturally relevant therapy to meet the needs of disabled women. Written in an accessible style with a minimum of jargon, this book provides clinical material from the perspectives of psychotherapists, clients, personal assistants, and health administrators. Women with Visible and Invisible Disabilities also highlights the importance of considering age, ethnicity, and sexual orientation in its ex

2. Record Nr.	UNISA996641268103316
Autore	Lan Xuguang
Titolo	Intelligent Robotics and Applications : 17th International Conference, ICIRA 2024, Xi'an, China, July 31 – August 2, 2024, Proceedings, Part II // edited by Xuguang Lan, Xuesong Mei, Caigui Jiang, Fei Zhao, Zhiqiang Tian
Pubbl/distr/stampa	Singapore : , : Springer Nature Singapore : , : Imprint : Springer, , 2025
ISBN	9789819607747 9819607744
Edizione	[1st ed. 2025.]
Descrizione fisica	1 online resource (659 pages)
Collana	Lecture Notes in Artificial Intelligence, , 2945-9141 ; ; 15202
Altri autori (Persone)	MeiXuesong JiangCaigui ZhaoFei TianZhiqiang
Disciplina	006.3
Soggetti	Artificial intelligence Software engineering Application software User interfaces (Computer systems) Human-computer interaction Computer networks Artificial Intelligence Software Engineering Computer and Information Systems Applications User Interfaces and Human Computer Interaction Computer Communication Networks
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Nota di contenuto	-- Robot Perception and Machine Learning. -- Sparse representation of robotic machining deformation based on key points determination. -- A Cross-media Localization Method for Amphibious Climbing Robot. -- YOWOv2: A Stronger yet Efficient Multi-level Detection Framework for Real-time Spatio-temporal Action Detection. -- Double Barrier Function Based Mutual Collision Avoidance Motion Planning Scheme

Synthesized by Varying-parameter Neural Network for Redundant Dual Manipulators. -- Multi-Scale Topology of Residual Network for Haze Removal. -- Multi-task Heterogeneous Framework for Semi-supervised Medical Image Segmentation. -- GI-Grasp: Target-Oriented 6DoF Grasping Strategy with Grasp Intuition Based on Vision-Language Models. -- S2NeRF: Neural Radiance Fields Training with Sparse Points and Sparse Views. -- Person Re-identification with Multi-stage Channel Feature Aggregation. -- Semi-Supervised Underwater Object Detection Using Grid Marker-Assisted Image Enhancement. -- Modality Mitigation And Diverse Part Awareness for Visible-Infrared Person Re-identification. -- Binocular Reconstruction and Monocular 6Dof Pose Estimation for Model Free Robot Grasping. -- Mip-NeRF+: Multi-Scale 3D Scene Synthesis. -- StereoNeRF: Learning Radiance Fields from Stereo Observation for Driving View Synthesis. -- Person Re-Identification Based on Random Occlusion for Local Feature Fusion. -- MDLIRE-Net: Semantic Segmentation of Point Clouds Based on Multidimensional Local Information Reencoding. -- Trajectory prediction method of flying uneven object based on improved Informer. -- Error Propagation Mechanism for the 2.5-D Grid Map Update in LiDAR Gaze Control Applications for Omni-directional Wheeled Robots. -- EMFIR: Efficient Dense Magnetic Field Mapping Based on Implicit Representation. -- MFap: Multi-view Feature Map for Visual Localization. -- Cognitive Intelligence and Security Control for Multi-domain Unmanned Vehicle Systems. -- Research on the Method of Trajectory Planning for Unmanned Aerial Vehicles in Complex Terrains Based on Reinforcement Learning. -- Research on functional safety-oriented supercapacitor vehicle-mounted low-voltage power supply system for new energy vehicles. -- Application of Stroke Extraction and Trajectory Planning in Robotic Calligraphy. -- Efficient Autonomous Exploration of Complex Environments Based on the Mobile Robot. -- Distributed Formation Coordinated Control of Multiple Unmanned Surface Vehicles Based on Deep Reinforcement Learning. -- A Hybrid Control Model for Platoons at Mixed-traffic Freeways Based on Deep Reinforcement Learning. -- Collision-Free Time-Varying Formation Control via Relative Localization. -- Design of Human-Machine Collaborative Assembly System based on Reconfigurable Processes. -- A Survey on Detecting Foreign Objects on Transmission Lines Based on UAV Images. -- Homogeneous Multi-Robot Patrolling Based on Humanoid Formation Configuration. -- All-in-one Image Restoration in Adverse Weather Conditions with Spatial-Frequency Domain Information. -- Distributed Adaptive Control of Multiple Robots for Cooperative Load Transportation. -- Research on Multi UAV Algorithm Based on Evolutionary Reinforcement learning.

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#### Sommario/riassunto

The 10-volume set LNAI 15201-15210 constitutes the proceedings of the 17th International Conference on Intelligent Robotics and Applications, ICIRA 2024, which took place in Xi'an, China, during July 31–August 2, 2024. The 321 full papers included in these proceedings were carefully reviewed and selected from 489 submissions. They were organized in topical sections as follows: Part I: Innovative Design and Performance Evaluation of Robot Mechanisms. Part II: Robot Perception and Machine Learning; Cognitive Intelligence and Security Control for Multi-domain Unmanned Vehicle Systems. Part III: Emerging Techniques for Intelligent Robots in Unstructured Environment; Soft Actuators and Sensors; and Advanced Intelligent and Flexible Sensor Technologies for Robotics. Part IV: Optimization and Intelligent Control of Underactuated Robotic Systems; and Technology and application of modular robots. Part V: Advanced actuation and intelligent control in medical robotics: Advancements in Machine Vision for Enhancing

Human-Robot Interaction; and Hybrid Decision-making and Control for Intelligent Robots. Part VI: Advances in Marine Robotics; Visual, Linguistic, Affective Agents: Hybrid-augmented Agents for Robotics; and Wearable Robots for Assistance, Augmentation and Rehabilitation of human movements. Part VII: Integrating World Models for Enhanced Robotic Autonomy; Advanced Sensing and Control Technologies for Intelligent Human-Robot Interaction; and Mini-Invasive Robotics for In-Situ Manipulation. Part VIII: Robot Skill Learning and Transfer; Human-Robot Dynamic System: Learning, Modelling and Control; AI-Driven Smart Industrial Systems; and Natural Interaction and Coordinated Collaboration of Robots in Dynamic Unstructured Environments. Part IX: Robotics in Cooperative Manipulation, MultiSensor Fusion, and Multi-Robot Systems; Human-machine Co-adaptive Interface; Brain inspired intelligence for robotics; Planning, control and application of bionic novel concept robots; and Robust Perception for Safe Driving. Part X: AI Robot Technology for Healthcare as a Service; Computational Neuroscience and Cognitive Models for Adaptive Human-Robot Interactions; Dynamics and Perception of Human-Robot Hybrid Systems; and Robotics for Rehabilitation: Innovations, Challenges, and Future Directions.

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