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Nota di contenuto	<p>Intro -- Foreword -- Preface -- Organization -- Contents - Part XXII --</p> <p>ByteTrack: Multi-object Tracking by Associating Every Detection Box --</p> <p>1 Introduction -- 2 Related Work -- 2.1 Object Detection in MOT --</p> <p>2.2 Data Association -- 3 BYTE -- 4 Experiments -- 4.1 Setting -- 4.2 Ablation Studies on BYTE -- 4.3 Benchmark Evaluation -- 5 Conclusion -- References -- Robust Multi-object Tracking by Marginal Inference</p> <p>-- 1 Introduction -- 2 Related Work -- 2.1 Similarity Computation --</p> <p>2.2 Matching Strategy -- 3 Method -- 3.1 Problem Formulation -- 3.2 Our Solution -- 3.3 Tracking Algorithm -- 4 Experiments -- 4.1 MOT Benchmarks and Metrics -- 4.2 Implementation Details -- 4.3 Evaluation of the Marginal Probability -- 4.4 Ablation Studies -- 4.5 Benchmark Evaluation -- 5 Conclusion -- References -- PolarMOT: How Far Can Geometric Relations Take us in 3D Multi-object Tracking?</p> <p>-- 1 Introduction -- 2 Related Work -- 3 Message Passing Networks for Multi-object Tracking -- 4 PolarMOT -- 4.1 Method Overview -- 4.2 Message Passing on a Sparse Multiplex Graph -- 4.3 Localized Relational Polar Encoding -- 4.4 Online Graph Construction -- 4.5 Implementation Details -- 5 Experimental Evaluation -- 5.1 Evaluation Setting -- 5.2 Benchmark Results -- 5.3 Model Ablation -- 5.4 Generalization Study -- 6 Conclusion -- References -- Particle Video Revisited: Tracking Through Occlusions Using Point Trajectories -- 1</p>

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