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Nota di contenuto	Intro -- Preface -- Organization -- Abstracts of Invited Tutorials -- Total Functional Programming in Idris: A Tutorial -- The Lean 4 Theorem Prover and Programming Language: A Tutorial -- Formally Reasoning about Distributed Systems using P -- Contents -- Invited Keynotes -- Formal Methods for Trusted Space Autonomy: Boon or Bane? -- 1 Introduction -- 2 Past Verification and Validation of Autonomy Flight Software -- 2.1 Remote Agent Experiment -- 2.2 Autonomous Sciencecraft on Earth Observing One -- 2.3 WATCH/SPOTTER on Mars Exploration Rovers -- 2.4 AEGIS on MER, MSL, and M2020 -- 2.5 MSL FSW -- 2.6 Intelligent Payload Experiment (IPEX) -- 3 Current Validation of Autonomy Software: Onboard Planner for M2020 -- 4 Discussion of Competing Verification and Validation Methods -- 4.1 Limitations of Testing and Informal Methods -- 4.2 Limitations of Formal Methods -- 5 Conclusions -- References -- An Essence of Domain Engineering -- 1 Introduction -- 1.1 What Is a Domain? -- 1.2 Structure of Paper -- 2 Philosophy: What Must be in any Domain Description? -- 2.1 The Search -- 2.2 Sørlander's Findings -- 2.3 The Basis -- 3 Elements of Domain Science and Engineering -- 3.1 Phenomena, Entities, Endurants and Perdurants -- 3.2 Endurants -- 3.3 Transcendental Deduction -- 3.4 Perdurants -- 3.5 The Domain Analysis and Description Process -- 4 An Example Domain Description -- 4.1 Endurants -- 4.2 Perdurants -- 5 Relevance to Aeronautics and

Space -- 5.1 But First -- 5.2 Air Traffic Control, ATC -- 5.3 An Aeronautics and Space Domain -- 6 Conclusion -- References --

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