1. Record Nr. UNISA996466246903316

Titolo	Intelligent Robotics and Applications : 4th International Conference, ICIRA 2011, Aachen, Germany, December 6-8, 2011, Proceedings, Part I / / edited by Sabina Jeschke, Honghai Liu, Daniel Schilberg
Pubbl/distr/stampa	Berlin, Heidelberg : , : Springer Berlin Heidelberg : , : Imprint : Springer, , 2011
ISBN	3-642-25486-1
Edizione	[1st ed. 2011.]
Descrizione fisica	1 online resource (XXIV, 643 p.)
Collana	Lecture Notes in Artificial Intelligence ; ; 7101
Disciplina	629.892
Soggetti	Artificial intelligence Optical data processing Pattern recognition Computer graphics Application software Computer communication systems Artificial Intelligence Image Processing and Computer Vision Pattern Recognition Computer Graphics Information Systems Applications (incl. Internet) Computer Communication Networks
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Bibliographic Level Mode of Issuance: Monograph
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Design of Compliant Bistable Mechanism for Rear Trunk Lid of Cars.

Sommario/riassunto

The two volume set LNAI 7101 and LNAI 7102 constitutes the refereed proceedings of the 4th International Conference on Intelligent Robotics and Applications, ICIRA 2011, held in Aachen, Germany, in November 2011. The 122 revised full papers presented were thoroughly reviewed and selected from numerous submissions. They are organized in topical sections on progress in indoor UAV, robotics intelligence, industrial robots, rehabilitation robotics, mechanisms and their applications, multi robot systems, robot mechanism and design, parallel kinematics, parallel kinematics machines and parallel robotics, handling and manipulation, tangibility in human-machine interaction, navigation and localization of mobile robot, a body for the brain: embodied intelligence in bio-inspired robotics, intelligent visual systems, self-optimising production systems, computational intelligence, robot control systems, human-robot interaction, manipulators and applications, stability, dynamics and interpolation, evolutionary robotics, bio-inspired robotics, and image-processing applications.