Record Nr. UNISA996466140803316 Artificial Evolution [[electronic resource]]: Third European Conference, **Titolo** AE '97, Nimes, France, October 22-24, 1997, Selected Papers // edited by Jin-Kao Hao, Evelyne Lutton, Edmund Ronald, Marc Schoenauer, **Dominique Snyers** Berlin, Heidelberg:,: Springer Berlin Heidelberg:,: Imprint: Springer, Pubbl/distr/stampa 1998 **ISBN** 3-540-69698-9 Edizione [1st ed. 1998.] Descrizione fisica 1 online resource (XII, 356 p.) Collana Lecture Notes in Computer Science, , 0302-9743 ; ; 1363 Disciplina 005.1 Soggetti Artificial intelligence Computers **Algorithms** Pattern recognition Artificial Intelligence Computation by Abstract Devices Algorithm Analysis and Problem Complexity Pattern Recognition Lingua di pubblicazione Inglese **Formato** Materiale a stampa Livello bibliografico Monografia Note generali Bibliographic Level Mode of Issuance: Monograph Nota di contenuto A template for scatter search and path relinking -- Representations, fitness functions and genetic operators for the satisfiability problem --Genetic algorithms at the edge of a dream -- Mimetic evolution --Adaptive penalties for evolutionary graph coloring -- An agent system for learning profiles in broadcasting applications on the Internet --Application of evolutionary algorithms to protein folding prediction --Telephone network traffic overloading diagnosis and evolutionary computation techniques -- Genetic algorithms for genetic mapping --Inverse problems for finite automata: A solution based on genetic

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dynamics on second order functions -- Asymptotical convergence rates

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Sommario/riassunto

This book constitutes the thoroughly refereed post-conference proceedings of the Third European Conference on Artificial Evolution, AE '97, held in Nimes, France, in October 1997. The volume presents 22 revised full papers carefully selected for inclusion together with an invited survey on the state-of-the-art in scatter search by Fred Glover. The papers are organized in topical sections on genetic-algorithm operators, applications in various areas, theoretical issues, methodologies, and evolvable hardware and robotics.