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Nota di contenuto	Similarity-based data localization in multi-agent systems -- A multi-agent flooding algorithm for search and rescue operations -- A practical security infrastructure for open multi-agent systems.
Sommario/riassunto	This book constitutes the refereed proceedings of the 11th German Conference on Multiagent System Technologies, MATES 2013, held in Koblenz, Germany, in September 2013. The 29 revised full papers and 3 keynote talks presented were carefully reviewed and selected from various submissions. The papers cover a broad area of topics of

interest ranging from issues of agent-based coordination to simulation to negotiation.
