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Soggetti	Artificial intelligence
	Optical data processing
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	Robotics
	Mechatronics
	Computers and civilization
	Application software
	User interfaces (Computer systems)
	Artificial Intelligence
	Computer Imaging, Vision, Pattern Recognition and Graphics
	Control, Robotics, Mechatronics
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Nota di contenuto	Industrial robot and robot manufacturing Mechanism and parallel robotics Machine and robot vision Robot grasping and control.
Sommario/riassunto	The three volume set LNAI 10462, LNAI 10463, and LNAI 10464 constitutes the refereed proceedings of the 10th International Conference on Intelligent Robotics and Applications, ICIRA 2017, held in Wuhan, China, in August 2017. The 235 papers presented in the

three volumes were carefully reviewed and selected from 310 submissions. The papers in this second volume of the set are organized in topical sections on industrial robot and robot manufacturing; mechanism and parallel robotics; machine and robot vision; robot grasping and control.