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Nota di contenuto	Intro -- Preface -- Organization -- Contents -- Workshop on Dynamic Risk managEment for AutonoMous Systems (DREAMS) -- Second Workshop on Dynamic Risk managEment for AutonoMous Systems (DREAMS) -- Workshop Description -- Towards a Software Component to Perform Situation-Aware Dynamic Risk Assessment for Autonomous Vehicles -- 1 Introduction -- 2 Situation-Aware Dynamic Risk Assessment (SINADRA) -- 3 SINADRA Python Implementation in CARLA -- 4 Usage Example: Front Vehicle Braking Risk -- 5 Conclusion and Outlook -- References -- Service-Oriented Reconfiguration in Systems of Systems Assured by Dynamic Modular Safety Cases -- 1 Introduction -- 2 Related Work -- 2.1 Dynamic Reconfiguration -- 2.2 Safety Assurance -- 3 Service-Oriented Reconfiguration -- 3.1 Service-Oriented Architecture -- 3.2 Blueprints and Configurations -- 3.3 Reconfiguration Sequence -- 4 Safe Reconfiguration Using Dynamic Modular Safety Cases -- 5 SoR Example Including DMSC Integration -- 6 Conclusion and Future Research -- References -- Behavior Prediction of Cyber-Physical Systems for Dynamic Risk Assessment -- 1 Introduction -- 2 Behavior Prediction Under Uncertainty -- 2.1 Calculating Reachable States -- 2.2 Modeling Agent Interactions -- 2.3 Illustrative Example -- 3 Risk Assessment -- 4 Conclusion -- References -- Autonomic Service Operation for Cloud Applications:

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