

1. Record Nr.	UNISA996396507503316
Autore	Vialart Charles <d. 1644.>
Titolo	The history of the government of France, under the administration of the great Armand du Plessis, Cardinall and Duke of Richlieu, and chief minister of state in that kingdome [[electronic resource]] : wherein occur many important negotiations relating to most part of Christendome in his time : with politique observations upon the chapters / / translated out of French by J.D. Esq
Pubbl/distr/stampa	London, : Printed by J. Macock, for Joshua Kirton ..., and are to be sold at the Kings Arms ..., 1657
Descrizione fisica	[8], 583 p. : port
Altri autori (Persone)	J. D (John Dodington)
Soggetti	France History Louis XIII, 1610-1643 France Politics and government 1610-1643
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Translation of Histoire du ministere d'Armand Jean du Plessis, cardinal duc de Richelieu, sous le regne de Louis le Juste, XIII, du nom roy de France et de Navarre. Advertisement: prelim. p. [8]. Extends from 1624 to 1633. First edition of this translation. The original was condemned to be burned by order of the Parliament of Paris, May 11, 1650. Reproduction of original in the University of Illinois (Urbana-Champaign Campus). Library.
Sommario/riassunto	eebo-0167

2. Record Nr.	UNINA9910437768803321
Titolo	21st Century Kinematics : The 2012 NSF Workshop / / edited by J. Michael McCarthy
Pubbl/distr/stampa	London : , : Springer London : , : Imprint : Springer, , 2013
ISBN	1-283-62230-0 9786613934758 1-4471-4510-0
Edizione	[1st ed. 2013.]
Descrizione fisica	1 online resource (250 p.)
Altri autori (Persone)	McCarthyJ. M
Disciplina	621.811
Soggetti	Automatic control Robotics Automation Mechanics Geometry, Algebraic Proteins Machinery Control, Robotics, Automation Classical Mechanics Algebraic Geometry Protein Biochemistry Machinery and Machine Elements
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Description based upon print version of record.
Nota di bibliografia	Includes bibliographical references.
Nota di contenuto	Computer-aided Invention of Mechanisms and Robots -- Mechanism Synthesis for Modeling Human Movement -- Algebraic Geometry and Kinematic Synthesis -- Numerical Algebraic Geometry and Kinematics -- Kinematic Analysis of Cable Robotic Systems.- Kinematic Synthesis of Compliant Mechanisms.- Protein Kinematics.
Sommario/riassunto	21st Century Kinematics focuses on algebraic problems in the analysis and synthesis of mechanisms and robots, compliant mechanisms, cable-driven systems and protein kinematics. The specialist contributors provide the background for a series of presentations at the

2012 NSF Workshop. The text shows how the analysis and design of innovative mechanical systems yield increasingly complex systems of polynomials, characteristic of those systems. In doing so, takes advantage of increasingly sophisticated computational tools developed for numerical algebraic geometry and demonstrates the now routine derivation of polynomial systems dwarfing the landmark problems of even the recent past. The 21st Century Kinematics workshop echoes the NSF-supported 1963 Yale Mechanisms Teachers Conference that taught a generation of university educators the fundamental principles of kinematic theory. As such these proceedings will be provide admirable supporting theory for a graduate course in modern kinematics and should be of considerable interest to researchers in mechanical design, robotics or protein kinematics or who have a broader interest in algebraic geometry and its applications.
