1. Record Nr. UNISA996395891403316

Autore	Frierson Henry
Titolo	A letter of a great victory obtained by Sir Miles Livesey, neer Kingstone, on Friday July 7. 1648 [[electronic resource]] : The Duke of Buckingham routed, where was slain, the Lord Francis Villers, the Duke of Buckinghams brother Col. Tho. Howard, the Earle of Berkshires son, 20 officers and souldiers, the Earle of Holland hurt, 200 wounded, 200 horse taken, 100 taken prisoners, &c
Pubbl/distr/stampa	London, : Printed by Robert Ibbitson in Smithfield neere to the Queens-Head Tavern, [1648]
Descrizione fisica	1 sheet ([1] p.)
Soggetti	Broadsides - England - London Great Britain History Civil War, 1642-1649 Campaigns Early works to 1800 Kingston upon Thames (London, England) Early works to 1800
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Signed at end of letter: Hen. Frierson. Publication date from Wing. Reproduction of original in the British Library.
Sommario/riassunto	eebo-0018

2. Record Nr. UNINA9910682589403321

Titolo	Robotics Research / / edited by Aude Billard, Tamim Asfour, Oussama Khatib
Pubbl/distr/stampa	Cham : , : Springer Nature Switzerland : , : Imprint : Springer, , 2023
ISBN	3-031-25555-0
Edizione	[1st ed. 2023.]
Descrizione fisica	1 online resource (579 pages)
Collana	Springer Proceedings in Advanced Robotics, , 2511-1264 ; ; 27
Disciplina	629.892
Soggetti	Automatic control Robotics Automation Computational intelligence Control, Robotics, Automation Computational Intelligence
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	It's just semantics: How to get robots to understand the world the way we do -- Learning Agile, Vision-Based Drone Flight: From Simulation to Reality -- Continual SLAM: Beyond Lifelong Simultaneous Localization and Mapping through Continual Learning -- Efficiently Learning Single-Arm Fling Motions to Smooth Garments -- Learning Long-Horizon Robot Exploration Strategies for Multi-Object Search in Continuous Action Spaces -- Visual Foresight with a Local Dynamics Model.
Sommario/riassunto	The proceedings of the 2022 edition of the International Symposium of Robotics Research (ISRR) offer a series of peer-reviewed chapters that report on the most recent research results in robotics, in a variety of domains of robotics including robot design, control, robot vision, robot learning, planning, and integrated robot systems. The proceedings entail also invited contributions that offer provocative new ideas, open-ended themes, and new directions for robotics, written by some of the most renown international researchers in robotics. As one of the pioneering symposia in robotics, ISRR has established some of the most fundamental and lasting contributions in the field since 1983. ISRR promotes the development and dissemination of ground-breaking

research and technological innovation in robotics useful to society by providing a lively, intimate, forward-looking forum for discussion and debate about the status and future trends of robotics, with emphasis on its potential role to benefit humans.