

1. Record Nr.	UNISA996383683003316
Autore	R. F
Titolo	A letter from a gentleman to the Honourable Ed. Howard, esq [[electronic resource]] : occasioned by a civiliz'd epistle of Mr. Dryden's, before his second edition of his Indian emperovr
Pubbl/distr/stampa	[London] In the Savoy, : Printed by Thomas Newcomb, 1668
Descrizione fisica	[2], 14 p
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Signed on p. 12: R.F. Reproduction of original in the Huntington Library.
Sommario/riassunto	eebo-0113

2. Record Nr.	UNINA9910346767703321
Autore	Petereit Janko
Titolo	Adaptive State
Pubbl/distr/stampa	KIT Scientific Publishing, 2016
ISBN	1000058693
Descrizione fisica	1 online resource (XXV, 241 p. p.)
Collana	Karlsruher Schriften zur Anthropomatik / Lehrstuhl für Interaktive Echtzeitsysteme, Karlsruher Institut für Technologie ; Fraunhofer-Inst. für Optronik, Systemtechnik und Bildauswertung IOSB Karlsruhe
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Sommario/riassunto	Mobile robot motion planning in unstructured dynamic environments is a challenging task. Thus, often suboptimal methods are employed which perform global path planning and local obstacle avoidance separately. This work introduces a holistic planning algorithm which is based on the concept of state