

1. Record Nr.	UNISA996313350403316
Titolo	The Classicist / / Institute for the Study of Classical Architecture
Pubbl/distr/stampa	New York, NY, : Institute for the Study of Classical Architecture, ©1994- New York, NY, : Institute of Classical Architecture and Classical America New York, NY, : Institute of Classical Architecture & Art
Descrizione fisica	1 online resource
Disciplina	720
Soggetti	Architecture, Classical Architecture, Classical - Influence Periodicals.
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Periodico
Note generali	Title from cover. Refereed/Peer-reviewed

2.	Record Nr.	UNICAMPANIAVAN00243894
	Autore	Cortese, Barbara
	Titolo	La tutela in caso di vizio della res empta e della res locata: inadempimento e rispondenza ex fide bona / Barbara Cortese
	Pubbl/distr/stampa	Roma, : RomaTre, 2020
	Titolo uniforme	La tutela in caso di vizio della res empta e della res locata
	Descrizione fisica	207 p. ; 23 cm
	Lingua di pubblicazione	Italiano Latino
	Formato	Materiale a stampa
	Livello bibliografico	Monografia
3.	Record Nr.	UNINA9910254181703321
	Autore	Dong Xiwang
	Titolo	Formation and Containment Control for High-order Linear Swarm Systems / / by Xiwang Dong
	Pubbl/distr/stampa	Berlin, Heidelberg : , : Springer Berlin Heidelberg : , : Imprint : Springer, , 2016
	ISBN	3-662-47836-6
	Edizione	[1st ed. 2016.]
	Descrizione fisica	1 online resource (182 p.)
	Collana	Springer Theses, Recognizing Outstanding Ph.D. Research, , 2190-5061
	Disciplina	629.8
	Soggetti	Control engineering System theory Control theory Artificial intelligence Control and Systems Theory Systems Theory, Control Complex Systems Artificial Intelligence
	Lingua di pubblicazione	Inglese
	Formato	Materiale a stampa
	Livello bibliografico	Monografia

Note generali	Description based upon print version of record.
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	Introduction -- Preliminaries -- Consensus control of swarm systems -- Formation control of swarm systems -- Containment control of swarm systems -- Formation-containment control of swarm systems -- Conclusions and future work.
Sommario/riassunto	This book focuses on analysis and design problems for high-order linear time-invariant (LTI) swarm systems (multi-agent systems) to achieve consensus, formation, containment and formation-containment. As a first step, the concepts of practical consensus and formation-containment are introduced. Unlike previous research, the formation in this book can be time-varying. A general framework for consensus, consensus tracking, formation, containment and state formation-containment is presented for the first time. Sufficient/necessary and sufficient conditions, and approaches to designing the protocols for swarm systems to achieve these control objectives, are respectively proposed. Autonomous time-varying formation experiments using five quadrotor unmanned aerial vehicles (UAVs) are conducted in an outdoor setting to demonstrate the theoretical results.