1. Record Nr. UNISA990003480860203316

Autore	PACE, Alessandro
Titolo	I limiti del potere / Alessandro Pace
Pubbl/distr/stampa	Napoli : Jovene, 2008
ISBN	88-243-1831-2
Descrizione fisica	XII, 193 p. ; 25 cm
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Soggetti	Presidenti della Repubblica - Responsabilità penale
Collocazione	XXIV.2.F. 202
Lingua di pubblicazione	Italiano
Formato	Materiale a stampa
Livello bibliografico	Monografia

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Titolo	Marine Robotics and Applications / / edited by Luc Jaulin, Andrea Caiti, Marc Carreras, Vincent Creuze, Frédéric Plumet, Benoît Zerr, Annick Billon-Coat
Pubbl/distr/stampa	Cham : , : Springer International Publishing : , : Imprint : Springer, , 2018
ISBN	3-319-70724-8
Edizione	[1st ed. 2018.]
Descrizione fisica	1 online resource (VIII, 178 p. 100 illus., 92 illus. in color.)
Collana	Ocean Engineering & Oceanography, , 2194-6396 ; ; 10
Disciplina	623.8205
Soggetti	Robotics Automation Vibration Dynamics Coasts Physics Robotics and Automation Vibration, Dynamical Systems, Control Coastal Sciences Numerical and Computational Physics, Simulation

Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Nota di bibliografia	Includes bibliographical references at the end of each chapters.
Sommario/riassunto	This book reports on findings at the intersection between two related fields, namely coastal hydrography and marine robotics. On one side, it shows how the exploration of the ocean can be performed by autonomous underwater vehicles; on the other side, it shows how some methods from hydrography can be implemented in the localization and navigation of such vehicles, e.g. for target identification or path finding. Partially based on contributions presented at the conference Quantitative Monitoring of Underwater Environment, MOQESM, held on October 11-12, 2016, Brest, France, this book includes carefully revised and extended chapters presented at the conference, together with original papers not related to the event. All in all, it provides readers with a snapshot of current methods for sonar track registration, multi-vehicles control, collective exploration of underwater environments, optimization of propulsion systems, among others. More than that, the book is aimed as source of inspiration and tool to promote further discussions and collaboration between hydrographers, robotic specialists and other related communities.