

1. Record Nr.	UNISA990002139610203316
Autore	PETRARCA, Francesco <1304-1374>
Titolo	Canzoniere / Francesco Petrarca ; edizione commentata a cura di Ugo Dotti
Pubbl/distr/stampa	Roma : Donzelli, 2004
ISBN	88-7989-851-5
Edizione	[Ed. aggiornata in occasione del 7. centenario della nascita di Francesco Petrarca]
Descrizione fisica	2 v. ; 18 cm.
Collana	Biblioteca ; 19
Disciplina	851.1
Collocazione	VI.3.A. 1718/1a (V A 1494/1) VI.3.A. 1718/2a (V A 1494/2)
Lingua di pubblicazione	Italiano
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	In custodia
Nota di contenuto	<vol. 1.> : CXIX, 439 p. - <vol. 2.> : P. 440-1015

2. Record Nr.	UNINA9910138305103321
Autore	Cubero Sam
Titolo	Industrial Robotics : Theory, Modelling and Control / / edited by Sam Cubero
Pubbl/distr/stampa	IntechOpen, 2006 Germany : , : Pro Literatur Verlag, Germany / ARS, Austria, , 2006
ISBN	953-51-5812-0
Edizione	[1st ed.]
Descrizione fisica	1 online resource (966 pages)
Disciplina	670.4272
Soggetti	Robotics
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Sommario/riassunto	This book covers a wide range of topics relating to advanced industrial robotics, sensors and automation technologies. Although being highly technical and complex in nature, the papers presented in this book represent some of the latest cutting edge technologies and advancements in industrial robotics technology. This book covers topics such as networking, properties of manipulators, forward and inverse robot arm kinematics, motion path-planning, machine vision and many other practical topics too numerous to list here. The authors and editor of this book wish to inspire people, especially young ones, to get involved with robotic and mechatronic engineering technology and to develop new and exciting practical applications, perhaps using the ideas and concepts presented herein.