

1. Record Nr.	UNIORUON00447379
Titolo	Collection Critique
Pubbl/distr/stampa	Paris, : V. Rasmussen
Lingua di pubblicazione	Non definito
Formato	Materiale a stampa
Livello bibliografico	Collezione
2. Record Nr.	UNINA9910483433303321
Titolo	Intelligent Robotics and Applications : 7th International Conference, ICIRA 2014, Guangzhou, China, December 17-20, 2014, Proceedings, Part I // edited by Xianmin Zhang, Honghai Liu, Zhong Chen, Nianfeng Wang
Pubbl/distr/stampa	Cham : , : Springer International Publishing : , : Imprint : Springer, , 2014
ISBN	3-319-13966-5
Edizione	[1st ed. 2014.]
Descrizione fisica	1 online resource (XXII, 514 p. 365 illus.)
Collana	Lecture Notes in Artificial Intelligence, , 2945-9141 ; ; 8917
Disciplina	629.892
Soggetti	Artificial intelligence Image processing - Digital techniques Computer vision Control engineering Robotics Automation Computers and civilization Application software Computers, Special purpose Artificial Intelligence Computer Imaging, Vision, Pattern Recognition and Graphics Control, Robotics, Automation Computers and Society Computer and Information Systems Applications Special Purpose and Application-Based Systems
Lingua di pubblicazione	Inglese

Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Bibliographic Level Mode of Issuance: Monograph
Nota di contenuto	Technical challenges.- Applications.- Biomedical applications -- Industrial automations -- Surveillance.- Sustainable mobility.
Sommario/riassunto	This two volume set LNAI 8917 and 8918 constitutes the refereed proceedings of the 7th International Conference on Intelligent Robotics and Applications, ICIRA 2014, held in Guangzhou, China, in December 2014. The 109 revised full papers presented were carefully reviewed and selected from 159 submissions. The papers aim at enhancing the sharing of individual experiences and expertise in intelligent robotics with particular emphasis on technical challenges associated with varied applications such as biomedical applications, industrial automations, surveillance, and sustainable mobility.