

1. Record Nr.	UNINA9911092503503321
Autore	Palmore Erdman B (Erdman Ballagh), <1930->
Titolo	Ageism : negative and positive / / Erdman B. Palmore
Pubbl/distr/stampa	New York, : Springer Pub., c1999
ISBN	1-281-86310-6 9786611863104 0-8261-7003-X
Edizione	[2nd ed.]
Descrizione fisica	1 online resource (281 p.)
Disciplina	305.26/0973
Soggetti	Ageism - United States Older people - United States
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Description based upon print version of record.
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	Contents; Foreword; Preface; Part I: Concepts; Part II: Causes And Consequences; Part III: Institutional Patterns; Part IV: Reducing Ageism; Appendix A: The Facts on Aging Quizzes; Appendix B: Ageist Humor; Appendix C: Annotated Bibliography; References; Index
Sommario/riassunto	In this updated edition, Palmore provides a comprehensive review of many different forms of ageism-including the interesting notion of positive ageism, which projects onto the elderly as a group traditional virtues like wisdom and thrift. He discusses both the individual and social influences on attitudes toward the aged; analyzes institutional patterns of ageism; and explores ways to used to reduce the impact of ageism on the elderly. This book is a valuable resource and text for students and professionals interested in the sociology of aging in our society. OLD COPY:.. Erdman Palmore has stud

2. Record Nr.	UNINA9911113271703321
Autore	Wang Xin
Titolo	Optimal Adaptive Cooperative Control for Nonlinear Multiagent Systems // by Xin Wang, Huaqing Li, Tingwen Huang
Pubbl/distr/stampa	Singapore : , : Springer Nature Singapore : , : Imprint : Springer, , 2026
ISBN	981-9529-64-6 9789819529643
Edizione	[1st ed. 2026.]
Descrizione fisica	1 online resource (309 pages)
Collana	Intelligent Technologies and Robotics Series
Altri autori (Persone)	LiHuaqing HuangTingwen
Disciplina	629.8312 003
Soggetti	Automatic control Computational intelligence Control and Systems Theory Computational Intelligence
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Nota di contenuto	Introduction -- Neural Network-based Adaptive Tracking Control for Nonlinear Multiagent Systems: The Observer Case -- Event-Triggered Cooperative Adaptive Neural Control for Cyberphysical Systems with Unknown State -- Event-triggered Adaptive Fault-tolerant Control for Nonlinear Multiagent Systems with Sensor and Actuator Faults -- Event-triggered Adaptive Finite-time Control for Switched Cyberphysical Systems with Uncertain Deception Attacks -- Adaptive Control for Uncertain Nonlinear Systems With Dynamic Full State Constraints: The SMDO Approach -- Observer-Based Event-Triggered Adaptive Control for Nonlinear Multiagent Systems with Unknown States and Disturbances -- Optimized Adaptive Finite-Time Consensus Control for Stochastic Nonlinear Multiagent Systems with Non-afne Nonlinear Faults -- Data-Driven Fault-Tolerant Reinforcement Learning Containment Control for Nonlinear Multiagent Systems.
Sommario/riassunto	This book provides a systematic and in-depth introduction to distributed optimal adaptive cooperative control for multiagent systems from a theoretical perspective. The major research topics include:

adaptive neural networks-based control schemes under multiconstraints, adaptive optimal control, event-triggered adaptive optimal control and data-based reinforcement learning control. The comprehensive and systematic treatment of adaptive optimal control in multiagent systems is one of the major features of the book, which is particularly suitable for readers who are interested in learning principles and methods for dealing with control resource constraints in multiagent systems and designing energy-saving control protocols. The book can benefit researchers, engineers, and graduate students in the fields of complex networks, smart grids, applied mathematics, electrical and electronic engineering, computer engineering, etc.
