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Nota di contenuto	-- Conversational Text-to-SQL: A Comprehensive Survey of Paradigms, Challenges, and Future Directions. -- Selecting the Most Specific Plan in AgentSpeak Programs. -- A wearable stereo vision-based obstacle detection system for visually impaired individuals. -- Towards Safe Action Policies in Multi-robot Systems with Causal Reinforcement Learning. -- A Formal Factorization Approach of Non-Deterministic Plans: Application to an Anti-Poaching Robotic Mission Scenario. -- Sim-to-Real 6-DoF Pose Estimation for UAVs using Synthetic RGB-D Data. -- Corroborative V&V for Autonomous Systems: Integrating Evidence and Discrepancy Analysis for Safety Assurance. -- BC-MPPI: A Probabilistic Constraint Layer for Safe Model-Predictive Path-Integral Control.
Sommario/riassunto	This book constitutes the proceedings of the 5th International Workshop on Agents and Robots for Reliable Engineered Autonomy, AREA 2025, which took place in Bologna, Italy, on October 25, 2025, in conjunction with ECAI 2025. The 8 full papers included in this book

were carefully reviewed and selected from 13 submissions. They deal with agent-oriented software engineering, robotic applications, formal verification, and artificial intelligence. .
