

1. Record Nr.	UNINA9911019873203321
Titolo	Tactile sensing and displays : haptic feedback for minimally invasive surgery and robotics // Saeed S. Sokhanvar ... [et al.]
Pubbl/distr/stampa	Chichester, West Sussex, : Wiley, c2013
ISBN	1-118-35798-1 1-299-18718-8 1-118-35796-5
Descrizione fisica	1 online resource (295 pages)
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Disciplina	152.182
Soggetti	Touch Computer-assisted surgery Robotics
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Description based upon print version of record.
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	Tactile Sensing and Displays; Contents; Preface; About the Authors; Chapter 1 Introduction to Tactile Sensing and Display; 1.1 Background; 1.2 Conventional and Modern Surgical Techniques; 1.3 Motivation; 1.4 Tactile Sensing; 1.5 Force Sensing; 1.6 Force Position; 1.7 Softness Sensing; 1.8 Lump Detection; 1.9 Tactile Sensing in Humans; 1.10 Haptic Sense; 1.10.1 Mechanoreception; 1.10.2 Proprioceptive Sense; 1.11 Tactile Display Requirements; 1.12 Minimally Invasive Surgery (MIS); 1.12.1 Advantages/Disadvantages of MIS; 1.13 Robotics; 1.13.1 Robotic Surgery; 1.14 Applications; References Chapter 2 Tactile Sensing Technologies2.1 Introduction; 2.2 Capacitive Sensors; 2.3 Conductive Elastomer Sensors; 2.4 Magnetic-Based Sensors; 2.5 Optical Sensors; 2.6 MEMS-Based Sensors; 2.7 Piezoresistive Sensors; 2.7.1 Conductive Elastomers, Carbon, Felt, and Carbon Fibers; 2.8 Piezoelectric Sensors; References; Chapter 3 Piezoelectric Polymers: PVDF Fundamentals; 3.1 Constitutive Equations of Crystals; 3.2 IEEE Notation; 3.3 Fundamentals of PVDF; 3.4 Mechanical Characterization of Piezoelectric Polyvinylidene Fluoride Films: Uniaxial and Biaxial 3.4.1 The Piezoelectric Properties of Uniaxial and Biaxial PVDF Films3.5

The Anisotropic Property of Uniaxial PVDF Film and Its Influence on Sensor Applications; 3.6 The Anisotropic Property of Biaxial PVDF Film and Its Influence on Sensor Applications; 3.7 Characterization of Sandwiched Piezoelectric PVDF Films; 3.8 Finite Element Analysis of Sandwiched PVDF; 3.8.1 Uniaxial PVDF Film; 3.8.2 Biaxial PVDF Film; 3.9 Experiments; 3.9.1 Surface Friction Measurement; 3.9.2 Experiments Performed on Sandwiched PVDF for Different Surface Roughness; 3.10 Discussion and Conclusions; References
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5.6 Results and Discussion; References; Chapter 6 Lump Detection; 6.1 Introduction; 6.2 Constitutive Equations for Hyperelasticity; 6.2.1 Hyperelastic Relationships in Uniaxial Loading; 6.3 Finite Element Modeling; 6.4 The Parametric Study; 6.4.1 The Effect of Lump Size; 6.4.2 The Effect of Depth; 6.4.3 The Effect of Applied Load; 6.4.4 The Effect of Lump Stiffness; 6.5 Experimental Validation; 6.6 Discussion and Conclusions; References; Chapter 7 Tactile Display Technology; 7.1 The Coupled Nature of the Kinesthetic and Tactile Feedback; 7.2 Force-Feedback Devices
7.3 A Review of Recent and Advanced Tactile Displays

Sommario/riassunto

Comprehensively covers the key technologies for the development of tactile perception in minimally invasive surgery Covering the timely topic of tactile sensing and display in minimally invasive and robotic surgery, this book comprehensively explores new techniques which could dramatically reduce the need for invasive procedures. The tools currently used in minimally invasive surgery (MIS) lack any sort of tactile sensing, significantly reducing the performance of these types of procedures. This book systematically explains the various technologies which the most prominent researchers
