

1. Record Nr.	UNINA9911019358503321
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Titolo	Global positioning systems, inertial navigation, and integration / / Mohinder S. Grewal, Lawrence R. Weill, Angus P. Andrews
Pubbl/distr/stampa	Hoboken, N.J., : Wiley-Interscience, c2007
ISBN	9786610822010 9781280822018 1280822015 9780470099728 0470099720 9780470099711 0470099712
Edizione	[2nd ed.]
Descrizione fisica	1 online resource (553 p.)
Altri autori (Persone)	WeillLawrence R <1938-> (Lawrence Randolph) AndrewsAngus P
Disciplina	910.282
Soggetti	Global Positioning System Inertial navigation Kalman filtering
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Description based upon print version of record.
Nota di bibliografia	Includes bibliographical references (p. 502-515) and index.
Nota di contenuto	GLOBAL POSITIONING SYSTEMS, INERTIAL NAVIGATION, AND INTEGRATION; CONTENTS; Preface to the Second Edition; Acknowledgments; Acronyms; 1 Introduction; 1.1 GNSS/INS Integration Overview; 1.2 GNSS Overview; 1.2.1 GPS; 1.2.2 GLONASS; 1.2.3 Galileo; 1.3 Differential and Augmented GPS; 1.3.1 Differential GPS (DGPS); 1.3.2 Local-Area Differential GPS; 1.3.3 Wide-Area Differential GPS; 1.3.4 Wide-Area Augmentation System; 1.4 Space-Based Augmentation Systems (SBASs); 1.4.1 Historical Background; 1.4.2 Wide-Area Augmentation System (WAAS); 1.4.3 European Geostationary Navigation Overlay System (EGNOS) 1.4.4 Japan's MTSAT Satellite-Based Augmentation System (MSAS) 1.4.5 Canadian Wide-Area Augmentation System (CWAAS); 1.4.6 China's Satellite Navigation Augmentation System (SNAS); 1.4.7 Indian GPS and GEO Augmented Navigation System (GAGAN); 1.4.8 Ground-Based

Augmentation Systems (GBASs); 1.4.9 Inmarsat Civil Navigation; 1.4.10 Satellite Overlay; 1.4.11 Future Satellite Systems; 1.5 Applications; 1.5.1 Aviation; 1.5.2 Spacecraft Guidance; 1.5.3 Maritime; 1.5.4 Land; 1.5.5 Geographic Information Systems (GISs), Mapping, and Agriculture; Problems

2 Fundamentals of Satellite and Inertial Navigation 2.1 Navigation Systems Considered; 2.1.1 Systems Other than GNSS; 2.1.2 Comparison Criteria; 2.2 Fundamentals of Inertial Navigation; 2.2.1 Basic Concepts; 2.2.2 Inertial Navigation Systems; 2.2.3 Sensor Signal Processing; 2.2.4 Standalone INS Performance; 2.3 Satellite Navigation; 2.3.1 Satellite Orbits; 2.3.2 Navigation Solution (Two-Dimensional Example); 2.3.3 Satellite Selection and Dilution of Precision; 2.3.4 Example Calculation of DOPs; 2.4 Time and GPS; 2.4.1 Coordinated Universal Time Generation; 2.4.2 GPS System Time

2.4.3 Receiver Computation of UTC 2.5 Example GPS Calculations with no Errors; 2.5.1 User Position Calculations; 2.5.2 User Velocity Calculations; Problems; 3 Signal Characteristics and Information Extraction; 3.1 Mathematical Signal Waveform Models; 3.2 GPS Signal Components, Purposes, and Properties; 3.2.1 50-bps (bits per second) Data Stream; 3.2.2 GPS Satellite Position Calculations; 3.2.3 C/A-Code and Its Properties; 3.2.4 P-Code and Its Properties; 3.2.5 L(1) and L(2) Carriers; 3.3 Signal Power Levels; 3.3.1 Transmitted Power Levels; 3.3.2 Free-Space Loss Factor

3.3.3 Atmospheric Loss Factor 3.3.4 Antenna Gain and Minimum Received Signal Power; 3.4 Signal Acquisition and Tracking; 3.4.1 Determination of Visible Satellites; 3.4.2 Signal Doppler Estimation; 3.4.3 Search for Signal in Frequency and C/A-Code Phase; 3.4.4 Signal Detection and Confirmation; 3.4.5 Code Tracking Loop; 3.4.6 Carrier Phase Tracking Loops; 3.4.7 Bit Synchronization; 3.4.8 Data Bit Demodulation; 3.5 Extraction of Information for Navigation Solution; 3.5.1 Signal Transmission Time Information; 3.5.2 Ephemeris Data; 3.5.3 Pseudorange Measurements Using C/A-Code

3.5.4 Pseudorange Measurements Using Carrier Phase

Sommario/riassunto

An updated guide to GNSS and INS, and solutions to real-world GPS/INS problems with Kalman filtering Written by recognized authorities in the field, this second edition of a landmark work provides engineers, computer scientists, and others with a working familiarity with the theory and contemporary applications of Global Navigation Satellite Systems (GNSS), Inertial Navigational Systems (INS), and Kalman filters. Throughout, the focus is on solving real-world problems, with an emphasis on the effective use of state-of-the-art integration techniques for those systems, especially the ap
