Record Nr. UNINA9911006647703321 Autore Kulakowski Bohdan T Titolo Dynamic modeling and control of engineering systems / / Bohdan T. Kulakowski, John F. Gardner, J. Lowen Shearer Cambridge;; New York,: Cambridge University Press, 2007 Pubbl/distr/stampa **ISBN** 1-139-93137-7 1-107-17844-4 0-511-80541-1 0-511-64924-X 0-511-28874-3 0-511-57318-9 0-511-28808-5 0-511-28942-1 Edizione [3rd ed.] Descrizione fisica 1 online resource (xii, 486 pages) : digital, PDF file(s) Altri autori (Persone) GardnerJohn F <1958-> (John Francis) ShearerJ. Lowen Disciplina 620.001/1 Soggetti Engineering - Mathematical models Systems engineering - Mathematical models Lingua di pubblicazione Inglese **Formato** Materiale a stampa Livello bibliografico Monografia Note generali Previous ed. cataloged as: Dynamic modeling and control of engineering systems / J. Lowen Shearer, Bohdan T. Kulakowski, John F. Gardner. Nota di bibliografia Includes bibliographical references and index. Mechanical systems -- Mathematic models -- Analytical solutions of Nota di contenuto system input-output equations -- Numerical solutions of ordinary differential equations -- Simulation of dynamic systems -- Electrical systems -- Thermal systems -- Fluid systems -- Mixed systems --System transfer functions -- Frequency analysis -- Closed-loop systems and system stability -- Control systems -- Analysis of discrete-time systems -- Digital control systems. Sommario/riassunto This textbook is ideal for a course in engineering systems dynamics and controls. The work is a comprehensive treatment of the analysis of lumped parameter physical systems. Starting with a discussion of mathematical models in general, and ordinary differential equations,

the book covers input/output and state space models, computer

simulation and modeling methods and techniques in mechanical, electrical, thermal and fluid domains. Frequency domain methods, transfer functions and frequency response are covered in detail. The book concludes with a treatment of stability, feedback control (PID, lead-lag, root locus) and an introduction to discrete time systems. This new edition features many new and expanded sections on such topics as: solving stiff systems, operational amplifiers, electrohydraulic servovalves, using Matlab with transfer functions, using Matlab with frequency response, Matlab tutorial and an expanded Simulink tutorial. The work has 40% more end-of-chapter exercises and 30% more examples.