

1. Record Nr.	UNINA9911006557103321
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Titolo	Control theory : a guided tour // James Ron Leigh
Pubbl/distr/stampa	London, : Institution of Engineering and Technology, 2012
ISBN	1-62198-559-8 1-299-10440-1 1-84919-228-6
Edizione	[3rd ed.]
Descrizione fisica	1 online resource (471 p.)
Collana	IET control engineering series ; ; 72
Disciplina	629.8312
Soggetti	Automatic control Control theory
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Description based upon print version of record.
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	Contents; Acknowledgements; Foreword by Professor Karl Astrom; Introduction; 1. Control concepts: a non-mathematical introduction; 2. Control design ideas: a non-mathematical treatment; 3. Synthesis of automatic feedback control loops: a more quantitative view; 4. How the Laplace transform greatly simplifies system representation and manipulation; 5. Frequency response methods; 6. Mathematical modelling; 7. Non-linear systems; 8. Limits to performance; 9. Some practical aspects of control design, implementation and justification; 10. Discrete time and digital control systems
Sommario/riassunto	Using clear tutorial examples, this fully-updated new edition concentrates on explaining and illustrating the concepts that are at the heart of control theory.