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Record Nr.	UNINA9911004775303321
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Titolo	Optimal Control Theory : An Introduction / Donald E. Kirk
Pubbl/distr/stampa	Mineola, N.Y. : , : Dover Publications, , 2004
ISBN	0-486-13507-1
	1-62198-596-2
Edizione	[1st ed.]
Descrizione fisica	1 online resource (761 pages)
Collana	Dover Books on Electrical Engineering
Disciplina	629.8312
Soggetti	Mathematical optimization
	Control theory
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Description based upon print version of record.
Nota di contenuto	Part I: Describing The System And Evaluating Its Performance -- Part II: Dynamic Programming -- Part III: The Calculus Of Variations And Pontryagin's Minimum Principle -- Part IV: Iterative Numerical Techniques For Finding Optimal Controls And Trajectories -- Part V: Conclusion
Sommario/riassunto	Optimal control theory is the science of maximizing the returns from and minimizing the costs of the operation of physical, social, and economic processes. Geared toward upper-level undergraduates, this text introduces three aspects of optimal control theory: dynamic programming, Pontryagin's minimum principle, and numerical techniques for trajectory optimization. Chapters 1 and 2 focus on describing systems and evaluating their performances. Chapter 3 deals with dynamic programming. The calculus of variations and Pontryagin's minimum principle are the subjects of chapters 4 and 5, and chapter 6 examines iterative numerical techniques for finding optimal controls and trajectories. Numerous problems, intended to introduce additional topics as well as to illustrate basic concepts, appear throughout the text.