Record Nr. UNINA9910299482503321 Autore Grebenstein Markus Titolo Approaching Human Performance: The Functionality-Driven Awiwi Robot Hand / / by Markus Grebenstein Pubbl/distr/stampa Cham:,: Springer International Publishing:,: Imprint: Springer,, 2014 **ISBN** 9783319035932 3319035932 Edizione [1st ed. 2014.] Descrizione fisica 1 online resource (XXXIV, 209 p. 164 illus., 133 illus. in color.) Collana Springer Tracts in Advanced Robotics, , 1610-7438; ; 98 Disciplina 629.8933 Soggetti Robotics Automation Artificial intelligence Robotics and Automation Artificial Intelligence Lingua di pubblicazione Inglese **Formato** Materiale a stampa Livello bibliografico Monografia Bibliographic Level Mode of Issuance: Monograph Note generali Nota di contenuto Analysis of the Current State of Robot Hands -- Analysis of the Human Hand -- The Awiwi Hand: An Arti cial Hand for the DLR Hand Arm System.- Results. Sommario/riassunto Humanoid robotics have made remarkable progress since the dawn of robotics. So why don't we have humanoid robot assistants in day-today life yet? This book analyzes the keys to building a successful humanoid robot for field robotics, where collisions become an unavoidable part of the game. The author argues that the design goal should be real anthropomorphism, as opposed to mere human-like appearance. He deduces three major characteristics to aim for when designing a humanoid robot, particularly robot hands: - Robustness against impacts - Fast dynamics - Human-like grasping and manipulation performance Instead of blindly copying human anatomy,

this book opts for a holistic design methodology. It analyzes human

functionalities that are the building blocks toward these necessary characteristics. They are the keys to designing an anthropomorphic

hands and existing robot hands to elucidate the important

robot hand, as illustrated in the high performance anthropomorphic Awiwi Hand presented in this book. This is not only a handbook for robot hand designers. It gives a comprehensive survey and analysis of the state of the art in robot hands as well as the human anatomy. It is also aimed at researchers and roboticists interested in the underlying functionalities of hands, grasping and manipulation. The methodology of functional abstraction is not limited to robot hands, it can also help realize a new generation of humanoid robots to accommodate a broader spectrum of the needs of human society.

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Sommario/riassunto

The purpose of Applied Geothermics for Petroleum Engineers is to present in a clear and concise form methods of utilizing the data of temperature surveys in deep boreholes as well as the results of field, laboratory and analytical investigations in geothermics to a wide audience. Although some aspects of the subject of this book have been discussed in several previous books and numerous papers, Applied Geothermics for Petroleum Engineers is the first book on this topic available to the petroleum engineering community. The objective of the book is to present the state of knowl