1. Record Nr. UNIORUON00500197

Autore	MENOCAL, María Rosa
Titolo	Shards of love : exile and the origins of the lyric / María Rosa Menocal
Pubbl/distr/stampa	Durham & London, : Duke University Press, 1994 ((rist.1999)
ISBN	978-08-223-1419-6
Descrizione fisica	xv, 295 p. ; 21 cm
Disciplina	809.0902
Soggetti	Letteratura medioevale - Studi
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia

2. Record Nr. UNINA9910983341303321

Autore	Lan Xuguang
Titolo	Intelligent Robotics and Applications : 17th International Conference, ICIRA 2024, Xi'an, China, July 31 – August 2, 2024, Proceedings, Part VII / / edited by Xuguang Lan, Xuesong Mei, Caigui Jiang, Fei Zhao, Zhiqiang Tian
Pubbl/distr/stampa	Singapore : , : Springer Nature Singapore : , : Imprint : Springer, , 2025
ISBN	9789819607808 9819607809
Edizione	[1st ed. 2025.]
Descrizione fisica	1 online resource (599 pages)
Collana	Lecture Notes in Artificial Intelligence, , 2945-9141 ; ; 15207
Altri autori (Persone)	MeiXuesong JiangCaigui ZhaoFei TianZhiqiang
Disciplina	006.3
Soggetti	Artificial intelligence Software engineering Application software User interfaces (Computer systems) Human-computer interaction Computer networks Artificial Intelligence Software Engineering Computer and Information Systems Applications

	User Interfaces and Human Computer Interaction Computer Communication Networks
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Nota di contenuto	-- Integrating World Models for Enhanced Robotic Autonomy. -- A CLIP guided model for few-shot object detection. -- A Robust 3D point clouds registration method. -- Research on 3D Point Cloud Classification Method Based on Depth Feature Reinforcement. -- Intelligent Defense Decision of Aircraft Based on Rainbow Algorithm. -- Structure design and control of magnetic levitated needle driving system. -- Design and Analysis of Key Equipment for Large Capacity Power Systems. -- A time-optimal and tracking-error controlled motion planning method for industrial robots. -- High Similarity Aircraft Connector Recognition Method Based on 3D Measurement. -- Abstract Hardware Grounding towards the Automated Design of Automation Systems. -- Design of a Mode-Switchable Elastic Actuator towards Interactive Robotic Applications. -- A High-Resolution Network for runway image detection. -- Advanced Sensing and Control Technologies for Intelligent Human-Robot Interaction. -- An Indirect Dataset Labeling Strategy of Acupoint Recognition with High-precision and High-efficiency for Physiotherapy Robot. -- Development and Modeling of Modular Cable-Driven Anthropomorphic Multi-Fingered Hands. -- Design of Brushless DC Motor Controller. -- Multi-turn Instruction Invocation on Human-Robot Interaction by Large Language Models. -- Master-Slave Control of Soft Robotic Glove Based on Carbon Black Strain Sensing. -- An optimized Joint Bilateral Guided filter for weld seam measurement based point cloud. -- Design and Control of a Wearable Upper-Limb Exoskeleton Featuring Force Feedback for Teleoperation. -- Investigation on grinding temperature evolutions and surface characteristics of CFRTP in robotic grinding. .- Design of Highly Integrated Microscale Fingertip Tactile Sensor for Robot Dexterous Hand. -- A Human–Robot Collaboration Framework Based on Human Collaboration Demonstration and Robot Learning. -- Mapping Human Hand Motion to Robotic Hand for Tools Manipulation: A Hybrid Mapping Method Based on Task Division. -- Mini-Invasive Robotics for In-Situ Manipulation. -- Principal Components Analysis Based Sticking for Drill Rod. -- An Obstacle Aided Inverse Kinematics Solver for Continuum Robotic Arm. -- A three-degree-of-freedom large-stroke flexible tip-tilt-piston stage driven by voice coil motor. -- Optimization of Electrostatic Adhesion Using Concentric Ring Electrodes. -- Motion control for continuum robots: A mini review for model-free and hybrid-model control. -- Study on the Mechanism of Band Gaps in Nonlinear Piezoelectric Metamaterials. -- A Dual-Loop Compensation Control Method to Improve Machining Accuracy for Robots with Secondary Encoders. -- Modeling and Analysis of Dynamic Electrostatic Adhesion Based on Triboelectric Nanogenerators. -- Variable Stiffness of Continuum Robotics: A Review. -- Hyper-redundant continuum robot: System development and feedback control.
Sommario/riassunto	The 10-volume set LNAI 15201-15210 constitutes the proceedings of

the 17th International Conference on Intelligent Robotics and Applications, ICIRA 2024, which took place in Xi'an, China, during July 31–August 2, 2024. The 321 full papers included in these proceedings were carefully reviewed and selected from 489 submissions. They were organized in topical sections as follows: Part I: Innovative Design and Performance Evaluation of Robot Mechanisms. Part II: Robot Perception and Machine Learning; Cognitive Intelligence and Security Control for Multi-domain Unmanned Vehicle Systems. Part III: Emerging Techniques for Intelligent Robots in Unstructured Environment; Soft Actuators and Sensors; and Advanced Intelligent and Flexible Sensor Technologies for Robotics. Part IV: Optimization and Intelligent Control of Underactuated Robotic Systems; and Technology and application of modular robots. Part V: Advanced actuation and intelligent control in medical robotics: Advancements in Machine Vision for Enhancing Human-Robot Interaction; and Hybrid Decision-making and Control for Intelligent Robots. Part VI: Advances in Marine Robotics; Visual, Linguistic, Affective Agents: Hybrid-augmented Agents for Robotics; and Wearable Robots for Assistance, Augmentation and Rehabilitation of human movements. Part VII: Integrating World Models for Enhanced Robotic Autonomy; Advanced Sensing and Control Technologies for Intelligent Human-Robot Interaction; and Mini-Invasive Robotics for In-Situ Manipulation. Part VIII: Robot Skill Learning and Transfer; Human-Robot Dynamic System: Learning, Modelling and Control; AI-Driven Smart Industrial Systems; and Natural Interaction and Coordinated Collaboration of Robots in Dynamic Unstructured Environments. Part IX: Robotics in Cooperative Manipulation, MultiSensor Fusion, and Multi-Robot Systems; Human-machine Co-adaptive Interface; Brain inspired intelligence for robotics; Planning, control and application of bionic novel concept robots; and Robust Perception for Safe Driving. Part X: AI Robot Technology for Healthcare as a Service; Computational Neuroscience and Cognitive Models for Adaptive Human-Robot Interactions; Dynamics and Perception of Human-Robot Hybrid Systems; and Robotics for Rehabilitation: Innovations, Challenges, and Future Directions.