1. Record Nr. UNISA996387937403316 Udall Ephraim <d. 1647.> Autore The Bishop of Armaghes direction, concerning the lyturgy, and Titolo episcopall government [[electronic resource]]: Being thereunto requested by the honourable, the House of Commons London,: Printed for A. B. and C. D., 1642 Pubbl/distr/stampa Descrizione fisica [8] p Soggetti Great Britain Religion 17th century Lingua di pubblicazione Inglese **Formato** Materiale a stampa Livello bibliografico Monografia Disavowed by the Bishop of Armagh and attributed to Ephraim Udall. Note generali Cf. B.M. Reproduction of original in Thomason Collection, British Library. Sommario/riassunto eebo-0018

2. Record Nr. UNINA9910983340603321 Autore Bradford Phillip G **Titolo** Proceedings of IEMTRONICS 2024: International IoT, Electronics and Mechatronics Conference, Volume 2 / / edited by Phillip G. Bradford, S. Andrew Gadsden, Shiban K. Koul, Kamakhya Prasad Ghatak Singapore:,: Springer Nature Singapore:,: Imprint: Springer,, 2025 Pubbl/distr/stampa **ISBN** 9789819747849 9819747848 Edizione [1st ed. 2025.] Descrizione fisica 1 online resource (647 pages) Collana Lecture Notes in Electrical Engineering, , 1876-1119; ; 1228 Altri autori (Persone) GadsdenS. Andrew KoulShiban K GhatakKamakhya Prasad Disciplina 004.678 Soggetti Internet of things **Telecommunication** Electric power production Internet of Things Communications Engineering, Networks **Electrical Power Engineering** Lingua di pubblicazione Inglese **Formato** Materiale a stampa Livello bibliografico Monografia Nota di contenuto Chapter 1; Al Algorithms for Dynamic Bandwidth Management in Wireless Networks -- Chapter 2: Comparative Analysis of Convolutional Neural Network-Based Counterfeit Detection: Keras vs. Pytorch -- Chapter 3: Stock Price Prediction Using Sentiment Based LSTM: S&P500 Vs Reddit Posts -- Chapter 4 :Size-Adaptive Convolutional Neural Network with Parameterized-Swish Activation for Enhanced Object Detection -- Chapter 5:Robo-CSK-Organizer: Commonsense Knowledge to Organize Detected Objects for Multipurpose Robots -- Chapter 6: Design of variable-radius kinematic metastructures for the control of belt drive transmission ratios --Chapter 7: Detection of Watermarks in Digital Images Using Filter Techniques and Convolutional Neural Networks -- chapter 8: RPL

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Sommario/riassunto

This book gathers selected research papers presented at IEMTRONICS 2024 (International IoT, Electronics and Mechatronics Conference), held during 3–5 April 2024 in London, United Kingdom in hybrid mode. This book presents a collection of state-of-the-art research work involving cutting-edge technologies in the field of IoT, electronics mechatronics, and related areas. The work is presented in two volumes.