

1. Record Nr.	UNINA9910984620303321
Autore	Pronko Leonard Cabell
Titolo	Avant-Garde : The Experimental Theater in France / / Leonard Cabell Pronko
Pubbl/distr/stampa	Berkeley, CA : , : University of California Press, , [1962] ©1962
ISBN	9780520313798 0520313798
Edizione	[4th printing, Reprint 2019]
Descrizione fisica	1 online resource (246 p.)
Disciplina	842.914
Soggetti	NON-CLASSIFIABLE
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Nota di contenuto	Frontmatter -- Preface -- Contents -- Illustrations -- 1. Many Avant-Gardes -- 2. Samuel Beckett -- 3. Eugène Ionesco -- 4. Theater and Anti-Theater -- 5. From Babel to Eden -- 6. Conclusion -- Appendix A: Metteurs en Scene of the Avant-Garde -- Appendix B: Avant-Garde Dramatists in English -- Notes -- Selected Bibliography
Sommario/riassunto	This title is part of UC Press's Voices Revived program, which commemorates University of California Press's mission to seek out and cultivate the brightest minds and give them voice, reach, and impact. Drawing on a backlist dating to 1893, Voices Revived makes high-quality, peer-reviewed scholarship accessible once again using print-on-demand technology. This title was originally published in 1962.

2. Record Nr.	UNINA9910983325803321
Autore	Ren Hongru
Titolo	Intelligent Control of Nonlinear Systems and Nonlinear Multi-Agent Systems with Complex Constraints : Unveiling Cutting-Edge Research and Insights / / by Hongru Ren, Hui Ma, Qi Zhou, Renquan Lu
Pubbl/distr/stampa	Singapore : , : Springer Nature Singapore : , : Imprint : Springer, , 2025
ISBN	9789819603206 981960320X
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Descrizione fisica	1 online resource (285 pages)
Collana	Intelligent Control and Learning Systems, , 2662-5466 ; ; 16
Altri autori (Persone)	MaHui ZhouQi LuRenquan
Disciplina	629.8312 003
Soggetti	Automatic control Control and Systems Theory
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Nota di contenuto	Introduction -- Prescribed Performance Control with Actuator Failures -- Approximation-Based Nussbaum Gain Adaptive Control with Periodic Disturbances -- Adaptive Dynamic Event-Triggered Control Using Disturbance Observer -- Adaptive Fuzzy Control with Output Constraint.
Sommario/riassunto	This book proposes an integrated design method for intelligent adaptive controllers to overcome the negative effects of various constraints on nonlinear systems and nonlinear multiagent systems in practical applications. The book rigorously provides problem analysis, controller design, and stability theory. In addition, numerous simulation examples are given to demonstrate the validity of the corresponding intelligent control methods, and the simulation results are illustrated in detail with graphs and tables. The methods proposed in this book eliminate some limitations of existing control methods in nonlinear systems and nonlinear multiagent systems with complex constraints and broaden the practical applications of intelligent control methods in industrial automation.

