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Autore	Sreberny Annabelle
Titolo	Persian service : the BBC and British interests in Iran / / by Annabelle Sreberny and Massoumeh Torfeh
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ISBN	9780755612413 0755612418 9780857724236 0857724231
Edizione	[First edition.]
Descrizione fisica	1 online resource (232 p.)
Collana	International Library of Iranian Studies ; ; 40
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Soggetti	Mass media - Political aspects - Iran Press and politics - Iran Communication studies
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Description based upon print version of record.
Nota di bibliografia	Includes bibliographical references.
Nota di contenuto	Introduction: The BBC World Service and Iran: Seventy Years of the Delicate Dance -- Chapter 1: From Propaganda to Public Diplomacy: The Changing Paradigms -- Chapter 2: The Establishment of the BBC World Service Persian Radio -- Chapter 3: The BBC World Service, the British Government and the Nationalisation of Iranian Oil -- Chapter 4: The BBC and the Iranian Revolution of 1979 -- Chapter 5: BBC Broadcasting to Afghanistan -- Chapter 6: Culture Wars and Foreign Policy: BBC Persian Television -- Chapter 7: Conclusion.
Sommario/riassunto	"Rumour and speculation in Iran have been rife for generations that the BBC has had a hand in every political upheaval in the country. In this vein the BBC has become a notable element in the complex and tortured narrative of Anglo-Iranian relations. The BBC Persian Service was initially developed in 1940 to prepare and broadcast British war-time propaganda. And it has since been seen by many in Iran as an integral part of British policy-making in the region. Thirty years ago, the Shah of Iran regarded the BBC Persian Service radio as his 'enemy number one' and held it responsible for promoting the revolution of

		1979. Only a couple decades earlier, the BBC Persian Service was widely accused for having been complicit in the CIA-led 1953 coup against Prime Minister Mohammad Musaddiq. And a decade earlier, the BBC Persian Service was strongly linked to the British-planned removal of Reza Shah in 1941. The BBC Persian service has frequently been perceived as an entity which was not simply a vehicle to record the changes occurring in Iran and throughout the Middle East, but rather an active agent of change. In this book, Annabelle Sreberny and Massoumeh Torfeh track the history of the BBC Persian Service, critically analysing both the assumptions that the BBC is a standard bearer for objective reporting and representations of it as a simple tool of Western interests. Also examining the history of relations between the Foreign Office and the BBC Persian Service, they demonstrate that these have never been pre-defined or rigid. Instead, they explore how both institutions have moved from an interest in what can crudely be called state-orchestrated 'propaganda' to a more subtle advocacy of fair and balanced journalism as the best agent of British values and influence."--Bloomsbury Publishing.

2.	Record Nr.	UNINA9910983487203321
	Autore	Mazal Jan
	Titolo	Modelling and Simulation for Autonomous Systems : 10th International Conference, MESAS 2023, Palermo, Italy, October 17–19, 2023, Revised Selected Papers / / edited by Jan Mazal, Adriano Fagiolini, Petr Vasik, Francesco Pacillo, Agostino Bruzzone, Stefan Pickl, Petr Stodola
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	Altri autori (Persone)	FagioliniAdriano VasikPetr PacilloFrancesco BruzzoneAgostino PicklStefan StodolaPetr
	Disciplina	003.3
	Soggetti	Computer simulation Computer Modelling
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	Formato	Materiale a stampa

Livello bibliografico	Monografia
Nota di contenuto	-- M&S of Intelligent Systems – R&D and Application. -- Comparison of Frequency Cepstral Coefficients in Impulse Acoustic Events Detection. -- Modelling and Simulation of hypersonic missile in VR-Forces environment. -- Atlas Fusion 2.0 - A ROS2 Based Real-Time Sensor Fusion Framework. -- UAS Flight Path Optimization Model for Effective Monitoring and Surveillance of the Buffer Zone in the UNFICYP Peacekeeping Mission. -- A Model-Based Design Approach for a System of Systems based on an Integrated UAV Platform. -- Practical applicability of tree spacing passability analysis on vehicle path planning. -- Where to go and how to get there: Tactical terrain analysis for military unmanned ground-vehicle mission planning. -- A Survey of Trajectory Planning Algorithms for Off-road Uncrewed Ground Vehicles. -- Multi-physics and Multi-spectral Sensors Simulator for Autonomous Flight Functions Development. -- Future Challenges of Advanced M&S Technology. -- Conceptual Aspects of Counter-UAS Modelling and Simulation. -- Challenges Associated with the Deployment of Autonomous Reconnaissance Systems on Future Battlefields. -- The Key Challenges of SBAD M&S. -- Development of Geoprocessing Tool for Wet Gap Crossing in Military Operations. -- Digital Twin Modeling for Machine Vision Testing in Autonomous Systems. -- A Situation Analysis Process in Computer-Generated Forces Team Behavior within Air Combat Simulations under Risk and Uncertainty: Concept and First Implementations. -- A Tactical Planning Process in Computer-Generated Forces Team Behavior within Air Combat Simulations: Concept and First Implementations. -- Survey on Sensing, Modelling and Reasoning Aspects in Military Autonomous Systems. -- AxS/AI in Context of Future Warfare and Security Environment. -- Camera based AI models used with lidar data for improvement of detected object parameters. -- The Analysis of Point Cloud Registration Methods for Natural Environment in Autonomous Driving. -- Hyperspectral Data Dimensionality Reduction: a Comparative Study between PCA and Autoencoder methods. -- Utilizing a CNN for Automatic Detection of Military Reconnaissance and Surveillance Objects in Aerial Images: Concept and Challenges. -- Multimodal Earth Observation Modeling using AI. -- Statistical Evaluation of Simulation Study Data. -- Mission: COMANND. Conceptualizing an AI Assistant for Decision-Making. -- Using Only Synthetic Images to Train a Drogue Detector for Aerial Refueling.
Sommario/riassunto	This volume LNCS 14615 constitutes the refereed proceedings of the 10th International Conference on Modelling and Simulation for Autonomous Systems, MESAS 2023, in October 17–19, 2023, in Palermo, Italy. The 21 full papers presented together with 4 short papers were carefully reviewed and selected from 49 submissions. The conference focuses to to unite the Modelling and Simulation and the Autonomous Systems/Robotic communities, creating a space for the exchange of innovative ideas and concept development. .