

1. Record Nr.	UNINA9910964624703321
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Titolo	Nonlinear Control Systems / / by Alberto Isidori
Pubbl/distr/stampa	London : , : Springer London : , : Imprint : Springer, , 1995
ISBN	1-84628-615-8
Edizione	[3rd ed. 1995.]
Descrizione fisica	1 online resource (xv, 549 pages) : illustrations
Collana	Communications and Control Engineering, , 2197-7119
Disciplina	629.892
Soggetti	Automatic control Robotics Automation System theory Control theory Automotive engineering Mathematical optimization Calculus of variations Control, Robotics, Automation Control and Systems Theory Systems Theory, Control Automotive Engineering Calculus of Variations and Optimization
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Bibliographic Level Mode of Issuance: Monograph
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	1. Local Decompositions of Control Systems -- 2. Global Decompositions of Control Systems -- 3. Input-Output Maps and Realization Theory -- 4. Elementary Theory of Nonlinear Feedback for Single-Input Single-Output Systems -- 5. Elementary Theory of Nonlinear Feedback for Multi-Input Multi-Output Systems -- 6. Geometric Theory of State Feedback: Tools -- 7. Geometric Theory of Nonlinear Systems: Applications -- 8. Tracking and Regulation -- 9. Global Feedback Design for Single-Input Single-Output Systems -- A. Appendix A -- A.1 Some Facts from Advanced Calculus -- A.2 Some Elementary Notions of Topology -- A.3 Smooth Manifolds -- A.4 Submanifolds -- A.5 Tangent Vectors -- A.6 Vector Fields -- B.

Sommario/riassunto

This established and authoritative text focuses on the design and analysis of nonlinear control systems. The author considers the latest research results and techniques in this updated and extended edition. Topics covered include: • local and global decompositions of control systems; • input-output maps and realization theory; • nonlinear feedback for single-input/single-output systems and multi-input/multi-output systems; • applications of state feedback; • output regulation and • global stabilization and disturbance attenuation. Examples are given from mechanical, electrical and aerospace engineering. The approach consists of a rigorous mathematical formulation of control problems and respective methods of solution. The two appendices outline the most important concepts of differential geometry and present some specific data not often found in other standard works. This makes Nonlinear Control Systems suitable as a graduate and undergraduate text and as a source of reference.