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Autore	Xiao Chengmo
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Nota di contenuto	Intro -- YACHT MODELLING AND ADAPTIVECONTROL -- YACHTMODELLINGANDADAPTIVECONTROL -- Contents -- List of Tables -- List of Figures -- Abstract -- Introduction -- 1.1. Introduction to Ship Motion Control Problem -- 1.2. Review on Ship Motion Control Strategies -- 1.3. Yacht Motion Control Problems -- 1.3.1. The Overlooked Study on Yacht Motion Control -- 1.3.2. What Is the Difference of Yacht Motion Control? -- 1.3.3. Why Adaptive Control? -- 1.4. What Is the New Contribution In This Book? -- 1.5. How Is This Book Organized? -- Yacht Mathematic Modelling: Hydrodynamics Analysis -- 2.1. Introduction -- 2.2. The Yacht Motion Coordinate Frame -- 2.3. Derivation of Motion Equations for Marine Vessels -- 2.3.1. A Particular Case of Ship Motion Analysis -- 2.3.2. The More General Case of Ship Motion Analysis -- 2.3.3. Simplification on Ship Motion Equations -- 2.4. Yacht Hydrodynamics Analysis -- 2.5. Disturbances Analysis -- 2.5.1. Wind Disturbance -- 2.5.2. Wave and Current Disturbances -- 2.6. SimulinkTM Implementation of the Chosen 12-metreAmerica's Cup Yacht -- 2.7. Summary -- Yacht

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Sommario/riassunto

The autopilot system which integrates the electronic hardware and the control algorithms has become standard use for commercial and military marine vessels, and is becoming essential equipment for smaller marine vessels such as leisure boats and yachts.