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Autore	Donativi Vincenzo
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Nota di contenuto	Cover -- Occhiello -- Dedicà -- Indice -- I Inquadramento sistematico Sezione I Natura giuridica. Nozione (e fattispecie) generale -- Sezione II Profili negoziali. Efficacia e rilevanza giuridica. Rimedi (negoziali e giudiziali) contro l'inadempimento -- II Le fattispecie di patti parasociali nel codice civile e nel TUF Sezione I Le fattispecie di patti parasociali nel codice civile -- Sezione II Verifica ulteriore della fattispecie codicistica in chiave funzionale: contro le ipotesi dottrinarie di correzione teleologica della fattispecie. Ratio legis tra contendibilità e concezioni revisioniste. Una diversa soluzione: contendibilità e affidamento su contendibilità attesa -- Sezione III Le fattispecie di patti parasociali nel TUF -- III La disciplina in tema di estensione temporale dei vincoli parasociali Sezione I La disciplina della durata e del recesso: premesse -- Sezione II Le sub-fattispecie su cui è imperniato il doppio binario normativo nel codice civile e nel TUF: patti "a tempo determinato" o "a tempo indeterminato" o che "prevedano" o "non prevedano un termine di durata" -- Sezione III Analisi critica della disciplina sulla durata -- Sezione IV La "neutralizzazione" del vincolo parasociale nelle quotazioni a fronte di offerte pubbliche -- IV La disciplina in tema di trasparenza e pubblicità dei patti parasociali Sezione I La disclosure dei patti parasociali nelle società aperte non quotate -- Sezione II La pubblicità dei patti parasociali nelle società con azioni quotate -- Bibliografia -- Giurisprudenza ordinaria e arbitrale -- Indice analitico.

2. Record Nr.	UNINA9910866579203321
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Acoustic Testing Principle -- 2.5 Model Establishment -- 2.6 Evaluating Indicator -- 3 Results and Discussions -- 3.1 Acoustic Signal Analysis -- 3.2 Principal Component Analysis Results -- 3.3 All Variable Modeling Results -- 3.4 Characteristic Variable Modeling Results -- 3.5 Discussion -- 4 Conclusions -- References -- A Human Digital Twin Based Framework for Human-Robot Hand-Over Task Intention Recognition -- 1 Introduction -- 2 Proposed Method -- 2.1 Construction of Human Digital Twin with Multimodal Data -- 2.2 Multiscale Feature Extraction Based on MSCNN-BiLSTM -- 2.3 Human-Robot Hand-Over Intention Classification -- 3 Experiment and Results -- 4 Conclusion -- References -- Design and Application of Data-Driven Visualization Platform for Dual Robotic Arms Assembly Process -- 1 Introduction -- 2 High-Fidelity Model Building for Assembly Process -- 2.1 Geometric Static Modeling -- 2.2 Logical Dynamic Modeling -- 2.3 Lightweight Treatment -- 3 Data-Driven Assembly Process Visualization -- 3.1 Real-Time Data Acquisition Method Based on Socket -- 3.2 Data Processing Method Based on Cubic Spline Interpolation -- 3.3 Real-Time Data Display Based on MQTT -- 3.4 WebGL Technology -- 3.5 Three.js Engine -- 3.6 LOD-Based Display Optimization -- 4 Platform Application -- References. An Innovative Design Method with Good Operability and Practicality.

Sommario/riassunto

This book gathers selected papers from 2023 International Conference on Mechanical Design (2023 ICMD), held in Chengdu, China. The main objectives are to bring the community of researchers in the fields of mechanical design together, to exchange and discuss the most recent investigations, challenging problems and new trends, and to encourage the wider implementation of the advanced design technologies and tools in the world, particularly throughout China. The theme of 2023 ICMD is “Innovative Design Drives High-Quality Development”, and the event devotes to providing an excellent forum for the scholars all around the world to share their innovative ideas, cutting-edge research results.
