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Nota di contenuto	1. An Overview of Non-minimum Phase Systems -- 2. Reduced-order SMC Design for Output Tracking in Non-Minimum Phase Systems : A Concept -- 3. Reduced-order Sliding Mode Control for High Performance Output Tracking in Non-minimum Phase Systems -- 4. Reduced Order SMC Design for Output Tracking of Arbitrary Signal -- 5. Output Tracking using Reduced Order SMC for Right-invertible Systems with Input Saturation.
Sommario/riassunto	This book focuses on the systematic design of reduced-order sliding mode output tracking control for non-minimum phase systems. It presents a systematic method for the design of reduced order control law for a wide variety of systems. The target audience primarily comprises research experts in control theory, but the book may also be beneficial for graduate students.

