1. Record Nr. UNISA996248290903316

Autore	Erskine John <1879-1951.>
Titolo	The Elizabethan lyric [[electronic resource]] : a study / / by John Erskine
Pubbl/distr/stampa	New York, : Columbia University Press, 1916
Descrizione fisica	xvi, 344 p. ; ; 23 cm
Collana	Columbia University studies in English ; ; v. 2
Soggetti	English poetry - Early modern, 1500-1700 - History and criticism Lyric poetry - History and criticism
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Reprint. Originally published: 1903.
Nota di bibliografia	Includes bibliographical references (p. 313-329) and index.

2.

Record Nr.	UNINA9910878066203321
Autore	Quaglia Giuseppe
Titolo	Advances in Italian Mechanism Science : Proceedings of the 5th International Conference of IFToMM Italy - Volume 2 / / edited by Giuseppe Quaglia, Giovanni Boschetti, Giuseppe Carbone
Pubbl/distr/stampa	Cham : , : Springer Nature Switzerland : , : Imprint : Springer, , 2024
ISBN	3-031-64569-3
Edizione	[1st ed. 2024.]
Descrizione fisica	1 online resource (578 pages)
Collana	Mechanisms and Machine Science, , 2211-0992 ; ; 164
Altri autori (Persone)	BoschettiGiovanni CarboneGiuseppe
Disciplina	629.892
Soggetti	Robotics Industrial engineering Production engineering Mechanics, Applied Robotic Engineering Industrial and Production Engineering Engineering Mechanics
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Nota di contenuto	Study Concerning Design and Optimization of a Multifunction Actuation Group for an Industrial Exoskeleton -- Finite element model updating applied to a lower limb prosthesis through the optimisation of its mechanical properties -- An Interactive Combined Mechatronic Approach to Enhance Upper Limb Rehabilitation -- Application of a multibody approach for the Digital Twinning of the human robot ecosystem in upper limb rehabilitation -- Effect of joint misalignment in upper limb exoskeleton based on McKibben muscles -- Estimating the Position of Surgical Needle Tips Hidden in Organs Using Generative Adversarial Networks -- Robot Assisted Rehabilitation mechatronic redesign of a finger exoskeleton to improve its motion tracking capabilities -- Upper Limbs Industrial Exoskeletons an Objective and Subjective Evaluation Method -- Design and Preliminary Testing of WELiBot A Wearable End Effector Type Upper Limb Assistive Robot -- Compact Series Elastic Actuator for a Wrist Exoskeleton for Daily Living

Assistance -- Ability Mining of Toe Manipulation Under Force Against Toe Flexion -- A feasibility study for a cable driven parallel robot for integrated wrist and fingers rehabilitation -- A 3D Printed Wearable Glove with Inflatable Chambers -- Analysis of bend-over gesture wearing a trunk support exoskeleton -- Anthropomorphic neck for a crash dummy -- eXoft Innovative Soft Rigid Exoskeleton for Smart Factory.

Sommario/riassunto

This book presents the proceedings of the 5th International Conference of IFToMM ITALY (IFIT), held in Turin, Italy on September 11–13, 2024. It includes peer-reviewed papers on the latest advances in mechanism and machine science, discussing topics such as biomechanical engineering, computational kinematics, the history of mechanism and machine science, gearing and transmissions, multi-body dynamics, robotics and mechatronics, the dynamics of machinery, tribology, vibrations, rotor dynamics and vehicle dynamics. A valuable, up-to-date resource, it offers an essential overview of the subject for scientists and practitioners alike and inspires further investigations and research.