1. Record Nr. UNINA9910877762303321 Autore Ikhouane Faycal Titolo Systems with hysteresis: analysis, identification and control using the Bouc-Wen model / / Faycal Ikhouane, Jose Rodellar Chichester, England;; Hoboken, NJ,: John Wiley, c2007 Pubbl/distr/stampa **ISBN** 1-280-97402-8 9786610974023 0-470-51320-9 0-470-51319-5 Descrizione fisica 1 online resource (224 p.) Altri autori (Persone) RodellarJose 621 Disciplina Soggetti Hysteresis - Mathematical models Lingua di pubblicazione Inglese **Formato** Materiale a stampa Livello bibliografico Monografia Description based upon print version of record. Note generali Nota di bibliografia Includes bibliographical references (p. [189]-197) and index. Nota di contenuto Systems with Hysteresis: Contents; Preface; List of Figures; List of Tables; 1 Introduction; 1.1 Objective and Contents of the Book; 1.2 The Bouc-Wen Model: Origin and Literature Review; 2 Physical Consistency of the Bouc-Wen Model; 2.1 Introduction; 2.2 BIBO Stability of the Bouc-Wen Model; 2.2.1 The Model; 2.2.2 Problem Statement; 2.2.3 Classification of the BIBO-Stable Bouc-Wen Models: 2.2.4 Practical Remarks; 2.3 Free Motion of a Hysteretic Structural System; 2.3.1 Problem Statement; 2.3.2 Asymptotic Trajectories; 2.3.3 Practical Remarks; 2.4 Passivity of the Bouc-Wen model 2.5 Limit Cases 2.5.1 The Limit Case n = 1; 2.5.2 The Limit Case alpha = 1; 2.5.3 The Limit Case alpha = 0; 2.5.4 The Limit Case beta+gamma = 0; 2.6 Conclusion; 3 Forced Limit Cycle Characterization of the Bouc-Wen Model; 3.1 Introduction; 3.2 Problem Statement; 3.2.1 The Class of Inputs; 3.2.2 Problem Statement; 3.3 The Normalized Bouc-Wen Model; 3.4 Instrumental Functions; 3.5 Characterization of the Asymptotic Behaviour of the Hysteretic Output; 3.5.1 Technical Lemmas; 3.5.2 Analytic Description of the Forced Limit Cycles for the Bouc-Wen Model: 3.6 Simulation Example: 3.7 Conclusion 4 Variation of the Hysteresis Loop with the Bouc-Wen Model Parameters 4.1 Introduction; 4.2 Background Results and Methodology

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Sommario/riassunto

Hysterisis is a system property that is fundamental to a range of engineering applications as the components of systems with hysterisis are able to react differently to different forces applied to them. Control theory is used to model these complex systems and cause them to behave in the desired manner; the Bouc-Wen model is a well-known semi-physical model that is used extensively to describe the hysterisis of systems in the areas of smart structures and civil engineering. The Bouc-Wen model for system hysterisis has increased in popularity due to its capability of capturing in an analytica