

1.	Record Nr.	UNINA990000537610403321
	Autore	Riv <s.p.a.>
	Titolo	Manuale dei cuscinetti : montaggio , manutenzione , lubrificazione / RIV
	Pubbl/distr/stampa	Torino : Villar Perosa, s.d.
	Descrizione fisica	23 cm ; 238 p.
	Locazione	DININ
	Collocazione	05 MA 19 49
	Lingua di pubblicazione	Italiano
	Formato	Materiale a stampa
	Livello bibliografico	Monografia
2.	Record Nr.	UNINA9910863275803321
	Autore	Khan Ameer Hamza
	Titolo	Management and Intelligent Decision-Making in Complex Systems: An Optimization-Driven Approach / / by Ameer Hamza Khan, Xinwei Cao, Shuai Li
	Pubbl/distr/stampa	Singapore : , : Springer Nature Singapore : , : Imprint : Springer, , 2021
	ISBN	9789811593925 9811593922
	Edizione	[1st ed. 2021.]
	Descrizione fisica	1 online resource (XI, 83 p. 39 illus., 35 illus. in color.)
	Disciplina	658.4033
	Soggetti	Control engineering Operations research Neural networks (Computer science) Control and Systems Theory Operations Research and Decision Theory Mathematical Models of Cognitive Processes and Neural Networks
	Lingua di pubblicazione	Inglese
	Formato	Materiale a stampa
	Livello bibliografico	Monografia

Nota di contenuto

Obstacle Avoidance Based Decision Making and Management of Articulated Agents -- Management of Soft Agents with Structural Uncertainty -- A Novel Damping Mechanism for Soft Agents with Structural Uncertainty -- Management of Electrical Machine Using Torque Control Strategy.

Sommario/riassunto

In this book, the authors focus on three aspects related to the development of articulated agents: presenting an overview of high-level control algorithms for intelligent decision-making of articulated agents, experimental study of the properties of soft agents as the end-effector of articulated agents, and accurate management of low-level torque-control loop to accurately control the articulated agents. This book summarizes recent advances related to articulated agents. The motive behind the book is to trigger theoretical and practical research studies related to articulated agents.
