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Autore	Luizzi Vincent
Titolo	Appeal to the people's court : rethinking law, judging, and punishment // by Vincent Luizzi
Pubbl/distr/stampa	Leiden ; Boston : , : Brill-Rodopi, , [2018] ©2018
ISBN	90-04-36571-0
Descrizione fisica	1 online resource (xi, 157 pages)
Collana	Value inquiry book series, , 0929-8436 ; ; Volume 318
Disciplina	340/.1
Soggetti	Justice, Administration of - Philosophy Jurisprudence - Philosophy Law - Philosophy Judgment Punishment Courts
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	People's courts and legal philosophy -- Spotlight on people's courts -- Law -- Judging -- Punishment.
Sommario/riassunto	In Appeal to the People's Court: Rethinking Law, Judging, and Punishment , Vincent Luizzi turns to the goings on in courts at the lowest level of adjudication for fresh insights for rethinking these basic features of the legal order. In the pragmatic tradition of turning from fixed and unchanging conceptions, the work rejects the view of law as a set of black and white rules, of judging as the mechanical application of law to facts, and of punishment as a necessary, punitive response to crime. The author, a municipal judge and philosophy professor, joins theory and practice to feature the citizen in rethinking these institutions. The work includes a foreword by Richard Hull, special Guest Editor for this volume in Studies in Jurisprudence.

2. Record Nr.

Titolo

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Advances in Physical Agents II : Proceedings of the 21st International Workshop of Physical Agents (WAF 2020), November 19-20, 2020, Alcalá de Henares, Madrid, Spain / / edited by Luis M. Bergasa, Manuel Ocaña, Rafael Barea, Elena López-Guillén, Pedro Revenga

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Descrizione fisica

1 online resource (XI, 362 p. 174 illus., 155 illus. in color.)

Collana

Advances in Intelligent Systems and Computing, , 2194-5365 ; ; 1285

Disciplina

006.3

Soggetti

Control engineering
Multiagent systems
Robotics
Computer vision
Control and Systems Theory
Multiagent Systems
Robotic Engineering
Computer Vision

Lingua di pubblicazione

Inglese

Formato

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Monografia

Note generali

Includes index.

Sommario/riassunto

The book reports on cutting-edge Artificial Intelligence (AI) theories and methods aimed at the control and coordination of agents acting and moving in a dynamic environment. It covers a wide range of topics relating to: autonomous navigation, localization and mapping; mobile and social robots; multiagent systems; human-robot interaction; perception systems; and deep-learning techniques applied to the robotics. Based on the 21st edition of the International Workshop of Physical Agents (WAF 2020), held virtually on November 19-20, 2020, from Alcalá de Henares, Madrid, Spain, this book offers a snapshot of the state-of-the-art in the field of physical agents, with a special emphasis on novel AI techniques in perception, navigation and human robot interaction for autonomous systems.

