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Nota di contenuto	Intro -- Organization -- Preface -- Contents -- Enhancing Human Augmentation: Analysis of Behavior Change in Highly Efficient Three-Hand Body After Motor Skill Training -- 1 Introduction -- 2 3-Arm Motor Skill Training System -- 2.1 Training Environment -- 2.2 Training on Spatial Awareness -- 2.3 Training on Cooperative Action -- 3 Experiment -- 3.1 Experimental Procedure -- 3.2 Evaluation Task -- 4 Result and Discussion -- 4.1 Change in Task Behavior -- 4.2 Discussion -- 4.3 Limitations -- 5 Conclusion -- References -- NeRF-YOLO: Detecting Occluded Objects via Multi-view Geometric Aggregation -- 1 Introduction -- 2 Related Work -- 2.1 Object Detection Under Occlusion -- 2.2 Neural Radiance Fields -- 3 Methodology -- 3.1 Feature Aggregation -- 3.2 Dataset Creation -- 4 Experimental Results -- 4.1 Metrics -- 4.2 Comparative Evaluation -- 5 Conclusion -- References -- A Fast-Acting Gripper for Aerial Vehicles -- 1 Introduction -- 2 Related Works -- 3 Mechanical Design -- 3.1 Active Claws -- 3.2 Passive Claws -- 3.3 Connection Rings -- 4 Results

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Sommario/riassunto

Gathering the proceedings of the 25th International Symposium on Measurement and Control in Robotics (ISMCR), held in Iasi, Romania, on September 21-22, 2023, this volume covers topics in the broad range of topics related to robotics and human robot systems, such as robot design innovations, sensors/smart sensors their integration/fusion, advanced controls and actuators, methods of AI in robotics, humanoid, climbing/walking, and autonomous robots; anthropomorphic robots, augmented/mixed/virtual reality (VR), intelligent CAD and IMS, visual/auditory/tactile/force displays, tools and techniques for

modelling VR systems, software architectures for VR, VR interaction and navigation techniques, distributed VR Systems, motion tracking, VR input and output devices, human factors in VR. The proceedings extend this platform to all researchers, scientists, industry experts, and students interested in these fields.