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Nota di contenuto	A Concise Overview of Safety Aspects in Human-Robot Interaction -- A Hybrid Control Approach for a Pneumatic-actuated Soft Robot -- BICEP: a Bio-Inspired Compliant Elbow Prosthesis -- Development of a Patient Behaviour Model for an Adaptive Medical Robot -- Emotion-Aware Control Framework for Human-Robot Collaboration.
Sommario/riassunto	Comprising sixteen independent chapters, this book covers recent advancements and emerging pathways within human-friendly robotics on physical and cognitive levels. Each chapter presents a novel work presented at HFR 2023 by researchers from various robotic domains, where new theories, methodologies, technologies, challenges, and empirical and experimental studies are discussed. The multidisciplinary nature of the authors enriches the compilation with varied viewpoints,

making it an excellent resource for academics, researchers, and industry professionals to get acquainted with the state of the art on human-robot interaction.
