1. Record Nr. UNINA9910832959603321 Autore Hover Franz S Titolo System Design for Uncertainty / Franz S. Hover, Michael S. Triantafyllou [s.l.]:,:[s.n.],,2009 Pubbl/distr/stampa Descrizione fisica 1 online resource (114 p.) Soggetti Science Lingua di pubblicazione Inglese **Formato** Materiale a stampa Livello bibliografico Monografia Sommario/riassunto The key ingredient in this course - and what differentiates it from many other related courses - is the uncertainty that is encountered whenever a built system is actually installed in the field. We may find uncertainty in the operating environment, whether it is a windy airspace, a bumpy road or an obstacle-strewn factory floor. We also find uncertainty in the parameters that define a system, for example, masses and stiffnesses and dampings, torque constants and physical size. Finally, since complex electromechanical systems involve sensors and actuators, we have to acknowledge uncertainty in measurement and feedback control. Ultimately, such systems are meant to accomplish specific objectives, and the designer's task is to achieve robustness,

performance and cost-effectiveness in the presence of uncertainty.

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Autore D'Arma Alessandro

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Nota di contenuto Cover -- Half Title -- Title page -- Copyright page -- Contents --

Preface: False Promises and Bright Futures -- Chapter 1: Public Service Journalism in Digital Markets -- Part I: Normative Frameworks --Chapter 2: Updating the Classics: The Roles and Principles of Public Service Journalism in the Digital Era -- Chapter 3: Digital Citizenship in the Middle East: The Tension Between Normative and Radical Approaches to Public Service -- Chapter 4: Public Service Media in the Platform Era: The Struggle to Stay News-Relevant -- Part II: Platform Power, Artificial Intelligence, and Public Service Journalism -- Chapter 5: Defining What's News: Digital Platforms and the Labelling of Public Service Media Outlets -- Chapter 6: Opportunities and Challenges of Artificial Intelligence in Public Media Journalism -- Chapter 7: Power Asymmetries in Public Service Journalism: Artificial Intelligence and the Intelligibility-Agency Problem -- Part III: National and Regional Case Studies -- Chapter 8: Public Service Media in the Crosshairs: National Policymaking Process, the EU Competition Regulation, and the Case of Yle's Text-Based News Content -- Chapter 9: Big Tech Platforms and News and Information Provision in Africa: An Assessment of Policy and Regulatory Challenges for Public Broadcasters -- Chapter 10: Digital Opportunity and State Authority: The Case of Doordashan News in the

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