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nonarchimedean reductive Lie groups"; "4.4. Geodesic polygons";
"Chapter 5. Weighted Configurations, Stability and the Relation to
Polygons"; "5.1. Gauss maps and associated dynamical systems";
"5.2. The polyhedron $D_{\text{sub}(n)}(X)$ "
"5.3. The polyhedron for the root system $B_{\text{sub}(2)}$ " "Chapter 6.
Polygons in Euclidean Buildings and the Generalized Invariant Factor
Problem"; "6.1. Folding polygons into apartments"; "6.2. A Solution
of Problem Q2 is not necessarily a solution of Problem Q3"; "Chapter
7. The Existence of Fixed Vertices in Buildings and Computation of the
Saturation Factors for Reductive Groups"; "7.1. The saturation factors
associated to a root system"; "7.2. The existence of fixed vertices";
"7.3. Saturation factors for reductive groups"; "Chapter 8. The
Comparison of Problems Q3 and Q4"
"8.1. The Hecke ring" "8.2. A geometric interpretation of $m_{\text{sub}(I_{\pm}, I^2, I^3)}(0)$ "; "8.3. The Satake transform"; "8.4. A solution of Problem Q4
is a solution of Problem Q3"; "8.5. A Solution of Problem Q3 is not
necessarily a solution of Problem Q4"; "8.6. The saturation theorem
for $GL(I)$ "; "8.7. Computations for the root systems $B_{\text{sub}(2)}$ and $G_{\text{sub}(2)}$ " "Appendix A. Decomposition of Tensor Products and
Mumford Quotients of Products of Coadjoint orbits"; "A. 1. The
existence of semistable triples and nonzero invariant vectors in triple
tensor products"
"A. 2. The semigroups of solutions to Problems Q1 and Q4" "Bibliography"
