

1. Record Nr.	UNINA9910827210603321
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Titolo	Global surgery formula for the Casson-Walker invariant // by Christine Lescop
Pubbl/distr/stampa	Princeton, New Jersey : , : Princeton University Press, , 1996 ©1996
ISBN	0-691-02133-3 1-4008-6515-8
Descrizione fisica	1 online resource (156 p.)
Collana	Annals of Mathematics Studies ; ; Number 10
Disciplina	514/.72
Soggetti	Surgery (Topology) Three-manifolds (Topology)
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Description based upon print version of record.
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	Front matter -- Table of contents -- Chapter 1. Introduction and statements of the results -- Chapter 2. The Alexander series of a link in a rational homology sphere and some of its properties -- Chapter 3. Invariance of the surgery formula under a twist homeomorphism -- Chapter 4. The formula for surgeries starting from rational homology spheres -- Chapter 5. The invariant A . for 3-manifolds with nonzero rank -- Chapter 6. Applications and variants of the surgery formula -- Appendix. More about the Alexander series -- Bibliography -- Index
Sommario/riassunto	This book presents a new result in 3-dimensional topology. It is well known that any closed oriented 3-manifold can be obtained by surgery on a framed link in S^3 . In Global Surgery Formula for the Casson-Walker Invariant, a function F of framed links in S^3 is described, and it is proven that F consistently defines an invariant, $\lambda(l)$, of closed oriented 3-manifolds. λ is then expressed in terms of previously known invariants of 3-manifolds. For integral homology spheres, λ is the invariant introduced by Casson in 1985, which allowed him to solve old and famous questions in 3-dimensional topology. λ becomes simpler as the first Betti number increases. As an explicit function of Alexander polynomials and surgery coefficients of framed links, the function F extends in a natural way to framed links in rational homology spheres.

It is proven that F describes the variation of I under any surgery starting from a rational homology sphere. Thus F yields a global surgery formula for the Casson invariant.
