

1. Record Nr.	UNINA9910825968103321
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Titolo	Multiple models approach in automation : takagi-sugeno fuzzy systems // Mohammed Chadli, Pierre Borne ; series editor, Bernard Dubuisson
Pubbl/distr/stampa	London, : ISTE Hoboken, N.J., : John Wiley and Sons Inc, 2013
ISBN	9781118577325 1118577329 9781299186590 1299186599 9781118577295 1118577299 9781118577226 1118577221
Edizione	[1st edition]
Descrizione fisica	1 online resource (204 p.)
Collana	Automation - control and industrial engineering series
Altri autori (Persone)	BornePierre DubuissonBernard
Disciplina	004.1 629.80151
Soggetti	Automation Fuzzy systems
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Description based upon print version of record.
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	Title Page; Contents; Notations; Introduction; Chapter 1. Multiple Model Representation; 1.1. Introduction; 1.2. Techniques for obtaining multiple models; 1.2.1. Construction of multiple models by identification; 1.2.2. Multiple model construction by linearization; 1.2.3. Multiple model construction by mathematical transformation; 1.2.4. Multiple model representation using the neural approach; 1.3. Analysis and synthesis tools; 1.3.1. Lyapunov approach; 1.3.2. Numeric tools: linear matrix inequalities; 1.3.3. Multiple model control techniques Chapter 2. Stability of Continuous Multiple Models2.1. Introduction; 2.2. Stability analysis; 2.2.1. Exponential stability; 2.3. Relaxed

stability; 2.4. Example; 2.5. Robust stability; 2.5.1. Norm-bounded uncertainties; 2.5.2. Structured parametric uncertainties; 2.5.3. Analysis of nominal stability; 2.5.4. Analysis of robust stability; 2.6. Conclusion; Chapter 3. Multiple Model State Estimation; 3.1. Introduction; 3.2. Synthesis of multiple observers; 3.2.1. Linearization; 3.2.2. Pole placement; 3.2.3. Application: asynchronous machine; 3.2.4. Synthesis of multiple observers

3.3. Multiple observer for an uncertain multiple model

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4.3. Observer-based controller

4.3.1. Unmeasurable decision variables;

4.4. Static output feedback control; 4.4.1. Pole placement; 4.5. Conclusion; Chapter 5. Robust Stabilization of Multiple Models; 5.1. Introduction; 5.2. State feedback control.; 5.2.1. Norm-bounded uncertainties; 5.2.2. Interval uncertainties; 5.3. Output feedback control; 5.3.1. Norm-bounded uncertainties; 5.3.2. Interval uncertainties; 5.4. Observer-based control; 5.5. Conclusion; Conclusion; APPENDICES; Appendix 1: LMI Regions; A1.1. Definition of an LMI region; A1.2. Interesting LMI region examples

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Sommario/riassunto

Much work on analysis and synthesis problems relating to the multiple model approach has already been undertaken. This has been motivated by the desire to establish the problems of control law synthesis and full state estimation in numerical terms. In recent years, a general approach based on multiple LTI models (linear or affine) around various function points has been proposed. This so-called multiple model approach is a convex polytopic representation, which can be obtained either directly from a nonlinear mathematical model, through mathematical transformation or through linearizat
