

1. Record Nr.	UNINA9910824857403321
Titolo	Recent developments in automatic control systems // editors, Yuriy P. Kondratenko [and three others]
Pubbl/distr/stampa	Gistrup, Denmark : , : River Publishers, , [2022] ©2022
ISBN	1-5231-5626-0 1-00-333922-0 1-003-33922-0 1-000-79228-5 87-7022-673-3
Edizione	[1st ed.]
Descrizione fisica	1 online resource (492 pages)
Collana	Automation, Control and Robotics
Disciplina	629.132/6
Soggetti	Automatic control
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	Front Cover -- Recent Developments in Automatic Control Systems -- Contents -- Preface -- List of Figures -- List of Tables -- List of Contributors -- List of Notations and Abbreviations -- Part I Advances in Theoretical Research of Control Systems -- 1 Control of Moving Object Groups in a Conflict Situation -- 1.1 Introduction -- 1.2 Function $w(n, v)$ , Encirclement by Pshenihnyi, Scheme of the Method of Resolving Functions -- 1.3 Group Pursuit of a Moving Object -- 1.4 Non-fixed Time of Game Termination -- 1.5 The Group Pursuit. Linear State Constraints -- 1.6 Principle of Shortest Broken Line in Successive Pursuit -- 1.7 Conclusion -- References -- 2 Applications of Variational Analysis to Controlled Sweeping Processes -- 2.1 Introduction and Discussions -- 2.2 Generalized Differentiation of Variational Analysis -- 2.3 Dynamic Optimization via Controlled Moving Sets -- 2.4 Sweeping Processes with Controlled Dynamics -- 2.5 Some Applications -- 2.6 Conclusion -- Acknowledgments -- References -- 3 Robust and Robustly-Adaptive Control of Some Noninvertible Memoryless Systems -- 3.1 Introduction -- 3.2 Problem Statement -- 3.3 Preliminaries -- 3.4 Robust Nonadaptive Control -- 3.5 Robustly-

Adaptive Control of Square Systems (Case 1) -- 3.6 Robustly-Adaptive Control of Square Systems (Case 2) -- 3.7 Robustly-Adaptive Control of Nonsquare Systems -- 3.8 Conclusion -- References -- 4 Nonlinear Integral Inequalities and Differential Games of Avoiding Encounter -- 4.1 Introduction -- 4.1.1 On the First Integral Inequalities -- 4.1.2 Development of the Theory of Integral Inequalities (Brief Survey) -- 4.2 Investigation of Nonlinear Holder Type Integral Inequality -- 4.2.1 Main Results -- 4.2.2 Applications of Integral Inequalities in Differential Games of Avoiding an Encounter -- 4.2.3 Comparison of Results -- 4.2.4 Remarks -- 4.3 Conclusion. Acknowledgments -- References -- 5 Principle of Time Dilation in Game Problems of Dynamics -- 5.1 Introduction -- 5.2 Statement of the Game Problem. Classic and Modified Pontryagin's Condition -- 5.3 Method Scheme -- 5.4 Main Statement -- 5.5 Example -- 5.6 Conclusion -- References -- 6 Method of Upper and Lower Resolving Functions for Pursuit Differential-difference Games with Pure Delay -- 6.1 Introduction -- 6.2 Statement of the Problem -- 6.3 Scheme of the Method -- 6.4 Conclusion -- References -- 7 Adaptive Method for the Variational Inequality Problem Over the Set of Solutions of the Equilibrium Problem -- 7.1 Introduction -- 7.2 Problem Formulation -- 7.3 Tikhonov-Browder Approximation -- 7.4 Algorithm -- 7.5 Proof of Algorithm Convergence -- 7.6 Algorithm for Two-Level Variational Inequalities -- 7.7 Conclusion -- Acknowledgments -- References -- Part II Advances in Control Systems Application -- 8 Identification of Complex Systems in the Class of Linear Regression Models -- 8.1 Introduction -- 8.2 Active Experiments and Informative Data -- 8.3 Method of Identification -- 8.3.1 Model Order Selection -- 8.3.2 SVD Parametric Identification -- 8.3.3 Total Model Reconstruction -- 8.3.4 Quasioptimal Model Dimensions -- 8.4 Simulation Results -- 8.4.1 Algorithm of identification -- 8.4.2 Excitation of system modes -- 8.4.3 Effect of Using the Signal Part of Matrices -- 8.4.4 Effect of Discarding Data Close to Noise -- 8.4.5 The Best Systems for Identification -- 8.4.6 Model Order Determination -- 8.4.7 Maximum Dimension of Identifiable Model -- 8.5 Conclusion -- References -- 9 Fuzzy Systems Design: Optimal Selection of Linguistic Terms Number -- 9.1 Introduction -- 9.2 Related Works and Problem Statement -- 9.3 Information Technology for Fuzzy Systems Design and Structural Optimization with Optimal Selection of Linguistic Terms Number. 9.4 Design and Structural Optimization of the Fuzzy Control System for the Quadrotor Unmanned Aerial Vehicle -- 9.5 Conclusion -- References -- 10 Analysis of the Dynamics and Controllability of an Autonomous Mobile Robot with a Manipulator -- 10.1 Introduction -- 10.2 Results of Study of Dynamics and Control of Autonomous Mobile Robots -- 10.2.1 Problem Statement -- 10.2.2 Design of an Autonomous Mobile Robot with a Manipulator -- 10.2.3 Dynamics Analysis -- 10.2.4 Analysis of AMR with M Controllability -- 10.3 Conclusion -- Acknowledgments -- References -- 11 Safe Navigation of an Autonomous Robot in Dynamic and Unknown Environments -- 11.1 Introduction -- 11.2 Related Works -- 11.3 Problem Statement -- 11.4 Fuzzy based Path Planning -- 11.5 Adjusting Speed -- 11.6 Experiments and Evaluations -- 11.7 Conclusion -- Acknowledgments -- References -- 12 Algorithmic Procedures Synthesis of Robust-Optimal Control for Moving Objects -- 12.1 Introduction -- 12.2 Problem Review -- 12.3 Optimal Synthesis -- 12.3.1 Optimal Trajectory Planning -- 12.3.2 Determining Switching Moments of Control Functions in the Feedback Loops -- 12.3.3 Synthesizing Optimal Control Functions in the Corresponding Feedback Loops -- 12.4 Robust Correction -- 12.5 Experiments -- 12.5.1 Sea Vessel

Maneuvering -- 12.5.2 Quadrotor UAV Stabilization -- 12.6 Conclusion  
 -- References -- Part III Recent Developments in Collaborative  
 Automation -- 13 Modeling of Cyber-Physical Systems -- 13.1  
 Introduction -- 13.2 Review of Modeling Methods for Cyber-Physical  
 Systems -- 13.3 Problem Formulation -- 13.4 Building Models of a  
 Logistic Cyber-Physical System -- 13.5 Simulation Results -- 13.6  
 Conclusion -- References -- 14 Reliability Control of Technical Systems  
 based on Canonical Decomposition of Random Sequences -- 14.1  
 Introduction -- 14.2 Problem Statement -- 14.3 Solution.  
 14.3.1 Forecasting the State of Control Objects -- 14.3.2 Identification  
 of Random Sequences Model' s Parameters based on Statistical  
 Goodness-of-fit Tests -- 14.3.3 Method of Reliability Control of  
 Technical Objects -- 14.4 Conclusion -- References -- 15 Petunin  
 Ellipsoids in Automatic Control Systems Design -- 15.1 Introduction --  
 15.2 Petunin Ellipses and Their Statistical Properties -- 15.2.1 Petunin  
 Ellipse and Ellipsoids -- 15.2.2 Petunin Ellipses and Linear Constraints  
 -- 15.2.3 Statistical Properties of Petunin' s Ellipses -- 15.2.4  
 Numerical Experiments -- 15.2.5 Prediction Sets -- 15.2.6 Hill' s  
 Assumption A(n) -- 15.2.7 Testing Statistical Properties for Petunin  
 Ellipses -- 15.3 Conclusion -- References -- 16 On Real-Time  
 Calculation of the Rejected Takeoff Distance -- 16.1 Introduction --  
 16.2 Dynamic Model of Aircraft Movement along the Runway -- 16.3  
 Analytical Solution of the Aircraft Motion Equation -- 16.4 Engine  
 Thrust Modelling During Switching off and Reverse -- 16.5 Rejected  
 Takeoff Distance Calculation -- 16.6 Interpolation of Aircraft  
 Parameters using Constant Values -- 16.7 Estimation of Speed, Path  
 and Time using Fixed Parameters of the Aircraft -- 16.8 Computer  
 Simulation -- 16.9 Emulation Results -- 16.10 Model Verification --  
 16.11 Conclusion -- References -- 17 Automated Control Problem for  
 Dynamic Processes Applied to Cryptocurrency in Financial Markets --  
 17.1 Introduction -- 17.1.1 Problem Statement -- 17.2 Cognitive  
 Mapping of Cryptocurrency Usage in Financial Markets -- 17.3 Design  
 of Unstable Cryptocurrency Rate Stabilization System -- 17.3.1  
 Experimental Study of the Stabilization System of Unstable  
 Cryptocurrency Rate -- 17.4 The Problem of Constrained Internal and  
 External Disturbances Suppression in Control of the Cryptocurrency CM  
 Impulse Process.  
 17.4.1 Algorithm for the State Controller Design for the CM Impulse  
 Process -- 17.4.2 Experimental Study of the System of Constrained  
 Internal and External Disturbances Suppression in the Cryptocurrency  
 CM Impulse Process Control -- 17.5 The Problem of Stabilizing the  
 Coordinates of Cryptocurrency CM Nodes at Given Levels Based on  
 Varying of Edge Weights and Nodes Coordinates -- 17.5.1 Design of a  
 Discrete Controller -- 17.5.2 Experimental Studies of the Stabilization  
 of Cryptocurrency CM Nodes Coordinates at Given Levels -- 17.6  
 Design of a System for Identifying CM Weighting Coefficients Based on  
 Recurrent Least Squares Method -- 17.7 Conclusion -- References --  
 Index -- About the Editors -- Back Cover.

## Sommario/riassunto

This monograph provides an overview of the recent developments in  
 modern control systems including new theoretical findings and  
 successful examples of practical implementation of the control theory  
 in different areas of industrial and special applications. Recent  
 Developments in Automatic Control Systems consists of extended  
 versions of selected papers presented at the XXVI International  
 Conference on Automatic Control "Automation 2020" (October 13-15,  
 2020, Kyiv, Ukraine) which is the main Ukrainian Control Conference  
 organized by the Ukrainian Association on Automatic Control (national  
 member organization of IFAC) and the National Technical University of

Ukraine "Igor Sikorsky Kyiv Polytechnic Institute". This is the third monograph in the River Publishers series in Automation, Control and Robotics based on the selected papers of the Ukrainian Control Conferences "Automation", in particular, the first monograph Control Systems: Theory and Applications (2018) was published based on "Automation - 2017" and the second monograph Advanced Control Systems: Theory and Applications was based on "Automation - 2018". The monograph is divided into three main parts: (a) Advances in Theoretical Research of Control Systems; (b) Advances in Control Systems Application; (c) Recent Developments in Collaborative Automation. The chapters have been structured to provide an easy-to-follow introduction to the topics that are addressed, including the most relevant references, so that anyone interested in this field can get started in the area. This book may be useful for researchers and students who are interesting in recent developments in modern control systems, robust adaptive systems, optimal control, fuzzy control, motion control, identification, modelling, differential games, evolutionary optimization, reliability control, security control, intelligent robotics and cyber-physical systems.

---