1. Record Nr. UNINA9910820577003321

Autore	Ballantyne Andrew
Titolo	Tudoresque : in pursuit of the ideal home / / Andrew Ballantyne & Andrew Law
Pubbl/distr/stampa	London, : Reaktion Books, 2011
ISBN	1-280-49397-6 9786613589200 1-78023-016-8
Edizione	[1st ed.]
Descrizione fisica	1 online resource (289 p.)
Altri autori (Persone)	LawAndrew
Disciplina	728
Soggetti	Architecture, Domestic - England - History Architecture, Tudor Decoration and ornament - Tudor style
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Description based upon print version of record.
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	Tudoresque cover; Imprint page; Contents; Preface; 1. An Indigenous Architecture; 2. Reviving a Tradition; 3. Tudoresque Paternalism; 4. Tudoresque Self-Reliance; 5. Backstage Tudoresque; 6. Britannia 'Outre-mer'; 7. A Global Brand: Beyond the Tropics and Back Again; References; Bibliography; Acknowledgements; Index
Sommario/riassunto	This is a perceptive, knowledgeable history of Tudor-style architecture, recognized around the world as a symbol of British identity. The book also explores the origin of the style in the 18th century, and traces its manifestations through the 19th and 20th centuries to the present day.

2. Record Nr. UNINA9910481961903321

Titolo	Intelligent robotics and applications [[electronic resource]] : third international conference, ICIRA 2010, Shanghai, China, November 10-12, 2010 : proceedings . Part I / / Honghai Liu ... [et al.] (eds.)
Pubbl/distr/stampa	Berlin, : Springer, 2010
ISBN	1-280-39010-7 9786613568021 3-642-16584-2
Edizione	[1st ed. 2010.]
Descrizione fisica	1 online resource (XXIII, 779 p. 525 illus.)
Collana	LNCS sublibrary. SL 7, Artificial intelligence Lecture notes in computer science, , 0302-9743 ; ; 6424. Lecture notes in artificial intelligence
Altri autori (Persone)	LiuHonghai
Disciplina	006.3
Soggetti	Robotics Robots - Programming Artificial intelligence
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Bibliographic Level Mode of Issuance: Monograph
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	Bionic Dextrous Hand -- Modeling and Control of Systems Involving Hysteresis -- Control System Modeling and Applications -- Intelligent Control and Their Applications -- Robot and Automation in Tunneling -- Robot Mechanism and Design -- Service Robotics -- Computer Vision and Applications -- Sensor Design, Multi-sensor Data Fusion.
Sommario/riassunto	The market demand for skills, knowledge and adaptability have positioned robotics to be an important field in both engineering and science. One of the most highly visible applications of robotics has been the robotic automation of many industrial tasks in factories. In the future, a new era will come in which we will see a greater success for robotics in non-industrial environments. In order to anticipate a wider deployment of intelligent and autonomous robots for tasks such as manufacturing, healthcare, ent- tainment, search and rescue, surveillance, exploration, and security missions, it is essential to push the frontier of robotics into a new dimension, one in which motion and intelligence play equally important roles. The 2010 International

Conference on Intelligent Robotics and Applications (ICIRA 2010) was held in Shanghai, China, November 10–12, 2010. The theme of the c- ference was “Robotics Harmonizing Life,” a theme that reflects the ever-growing interest in research, development and applications in the dynamic and exciting areas of intelligent robotics. These volumes of Springer’s Lecture Notes in Artificial Intel- gence and Lecture Notes in Computer Science contain 140 high-quality papers, which were selected at least for the papers in general sessions, with a 62% acceptance rate Traditionally, ICIRA 2010 holds a series of plenary talks, and we were fortunate to have two such keynote speakers who shared their expertise with us in diverse topic areas spanning the rang of intelligent robotics and application activities.