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Altri autori (Persone)	PhamAnh Tuan (Engineer)
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Note generali	Description based upon print version of record.
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	Cover; Title Page; Table of Contents; Introduction; Chapter 1. 0D Analytical Modeling of Airplane Motions; 1.1. References: axis systems on use; 1.1.1. Galilean reference: R0; 1.1.2. Airplane reference: RB (body) also called "linked reference"; 1.1.3. Resultant angular velocity; 1.2. Equations of motion of the airplane; 1.2.1. Expression of Newton's principle; 1.2.2. Expression of the dynamic momentum; 1.3. Description of external forces and torques; 1.3.1. Aerodynamic forces and torques; 1.3.2. Sign rules; 1.4. Description of aerodynamic coefficients; 1.4.1. Drag coefficient: Cx 1.4.2. Side lift coefficient: CY1.4.3. Vertical lift due to attack angle: CZ; 1.4.4. Lift due to pitch angular velocity: CZq; 1.4.5. Roll coefficients (due to , l , p); 1.4.6. Pitch coefficients (due to , m , q , static curvature); 1.4.7. Yaw coefficients (due to , n, r); 1.5. Aerodynamic data of a supersonic airliner for valuation of the software; 1.6. Horizontal flight as an initial condition; 1.7. Effect of gravitational forces; 1.8 calculation of the trajectory of the airplane in open space; 1.9. Validation by comparison with ONERA Concorde data 1.10. Definitions of aerodynamic coefficients and derivatives 1.10.1.1.10.1. Aerodynamic coefficients; 1.10.2. Total lift coefficient;

1.10.3. Drag characteristics: (dimensionless); 1.10.4. Side lift coefficient: C_Y (dimensionless); 1.10.5. Roll coefficients; 1.10.6. Pitch coefficients; 1.10.7. Yaw coefficients; Chapter 2. Design and Optimization of an Unmanned Aerial Vehicle (UAV); 2.1. General design of the drone; 2.2. Weight estimation; 2.3. Size estimation; 2.4. Mass and inertia evaluation; 2.4.1. Mass evaluation; 2.4.2. Measurement of the roll inertia (A) 2.4.3. Measurement of pitch inertia (B) 2.4.4. Measurement of yaw inertia (C); 2.5. Convergence toward the target; Chapter 3. Organization of the Auto-Pilot; 3.1. Position of the drone in open space; 3.2. The Dog Law; 3.3. Flight tests; 3.4. Altitude control system; 3.5. Altitude measurement on an actual drone; Bibliography; Index

Sommario/riassunto

In the field of aeronautical dynamics, this book offers readers a design tool which enables them to solve the different problems that can occur during the planning stage of a private project. The authors present a system for the modeling, design and calculation of the flying qualities of airplanes and drones, with a complete mathematical model by Matlab/Simulink. As such, this book may be useful for design engineers as well as for keen airplane amateurs. The authors expound the various phases involved in the design process of an airplane, starting with the formulation of a design tool, un

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Autore	Thirunavukkarasu I
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ISBN	9789819758661 9819758661
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Collana	Lecture Notes in Electrical Engineering, , 1876-1119 ; ; 1236
Altri autori (Persone)	KumarRoshan
Disciplina	629.8
Soggetti	Automatic control Robotics Automation Electronics Signal processing Power electronics Control, Robotics, Automation Electronics and Microelectronics, Instrumentation Digital and Analog Signal Processing Power Electronics
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Nota di contenuto	Automation -- Bio medical Instrumentation -- Control Systems -- Computing Data Analytics -- Digital Signal Processing -- Distributed Control System.
Sommario/riassunto	This book presents the select proceedings of the Control Instrumentation and System Conference (CISCON 2023) held at Manipal Institute of Technology, MAHE, Manipal. It examines a broad spectrum covering the latest trends in instrumentation, sensors and systems, and industrial automation and control. The topics covered include image and signal processing, robotics, renewable energy, power systems, and power drives, performance attributes of MEMS, multi-sensor data fusion, machine learning, optimization techniques, process control, safety monitoring, safety-critical control, supervisory control, system

modeling, and virtual instrumentation. The book is a valuable reference for researchers and professionals interested in sensors, adaptive management, automation and control, and allied fields.
