

1. Record Nr.	UNINA9910455280103321
Autore	Head John W (John Warren), <1953->
Titolo	Losing the global development war [[electronic resource]] : a contemporary critique of the IMF, the World Bank, and the WTO // John W. Head
Pubbl/distr/stampa	Leiden, : Martinus Nijhoff Publishers, c2008
ISBN	1-282-39759-1 9786612397592 90-474-4036-6
Descrizione fisica	1 online resource (368 p.)
Collana	Nijhoff eBook titles 2008
Disciplina	332.1/53
Soggetti	Development banks - Evaluation Economic assistance Electronic books.
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Description based upon print version of record.
Nota di bibliografia	Includes bibliographical references (p. 331-337) and index.
Nota di contenuto	Preliminary Material / J.W. Head -- Chapter One. The Fourth World War / J.W. Head -- Chapter Two. A Cacophony Of Criticisms—Attacking The Global Economic Organizations / J.W. Head -- Chapter Three. What Are The Global Economic Organizations? / J.W. Head -- Chapter Four. Battles Over The Geos' Policies And Operations / J.W. Head -- Chapter Five. Battles Over The Geos' Character, Control, And Reach / J.W. Head -- Chapter Six. The Current Front In The Global Development War—How (And Whether) To Reform The Geos? / J.W. Head -- About The Author / J.W. Head -- Selected Bibliography / J.W. Head -- Index / J.W. Head.
Sommario/riassunto	This book offers a new perspective in examining the key global economic organizations - the International Monetary Fund, the World Bank (and its regional counterparts), and the World Trade Organization. Aimed at ordinary informed readers, the text draws upon the author's many years of familiarity with these organizations to evaluate them from a legal and policy perspective, touching on issues of 'mission creep,' 'democracy deficit,' and more. The book depicts such issues as the central struggles in a 'Global Development War' that is now

being lost because of certain ideological and institutional failings that currently afflict the global institutions. That war can be won, the author asserts, only by adopting an ideology of liberal, intelligent, participatory, multilateral, and sustainable human development.

2. Record Nr.	UNINA9910819758303321
Autore	Goodman Michael K. J. <1952->
Titolo	An introduction to the early development of mathematics // Michael K. J. Goodman
Pubbl/distr/stampa	Chichester, West Sussex, England : , : Wiley, , 2016
ISBN	111910498X 9781119104988
Descrizione fisica	1 online resource (252 pages)
Disciplina	510.9/014
Soggetti	Mathematics - History Mathematics, Ancient
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Nota di bibliografia	Includes bibliographical references and index.

3. Record Nr.	UNINA9910566471903321
Autore	Hang Peng
Titolo	Actuators for Intelligent Electric Vehicles
Pubbl/distr/stampa	Basel, : MDPI - Multidisciplinary Digital Publishing Institute, 2022
Descrizione fisica	1 online resource (330 p.)
Soggetti	History of engineering and technology Mechanical engineering and materials Technology: general issues
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Sommario/riassunto	This book details the advanced actuators for IEVs and the control algorithm design. In the actuator design, the configuration four-wheel independent drive/steering electric vehicles is reviewed. An in-wheel two-speed AMT with selectable one-way clutch is designed for IEV. Considering uncertainties, the optimization design for the planetary gear train of IEV is conducted. An electric power steering system is designed for IEV. In addition, advanced control algorithms are proposed in favour of active safety improvement. A supervision mechanism is applied to the segment drift control of autonomous driving. Double super-resolution network is used to design the intelligent driving algorithm. Torque distribution control technology and four-wheel steering technology are utilized for path tracking and adaptive cruise control. To advance the control accuracy, advanced estimation algorithms are studied in this book. The tyre-road peak friction coefficient under full slip rate range is identified based on the normalized tyre model. The pressure of the electro-hydraulic brake system is estimated based on signal fusion. Besides, a multi-semantic driver behaviour recognition model of autonomous vehicles is designed using confidence fusion mechanism. Moreover, a mono-vision based lateral localization system of low-cost autonomous vehicles is proposed with deep learning curb detection. To sum up, the discussed

advanced actuators, control and estimation algorithms are beneficial to the active safety improvement of IEVs.
